

变 器 HF610 列

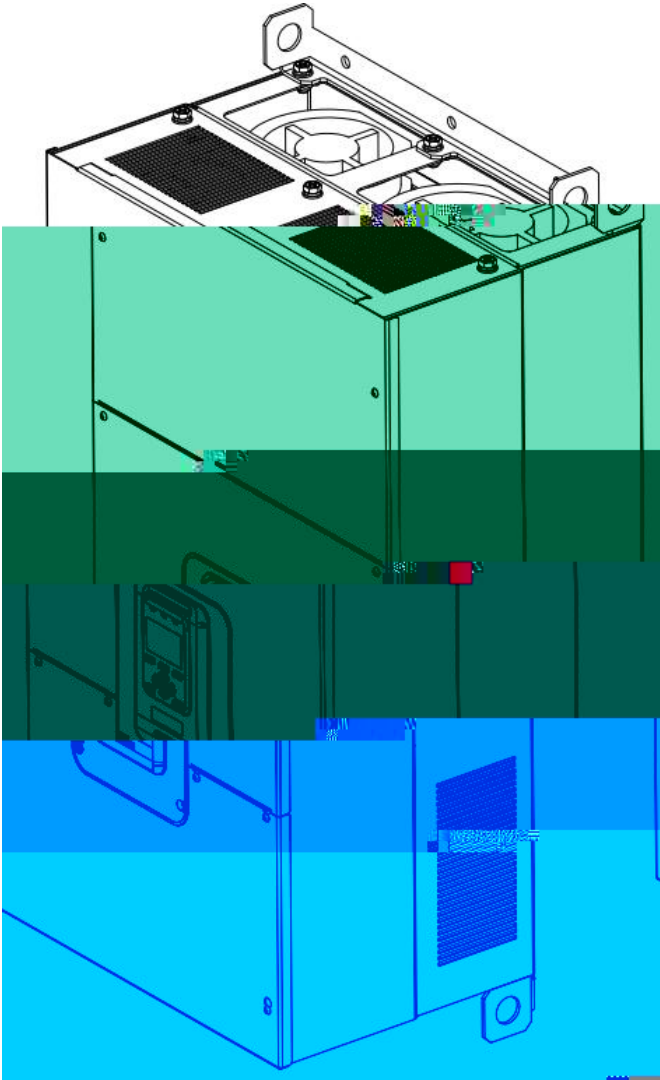
使 书 : 1.09

书交 , 妥善保。

1.4

份 公司

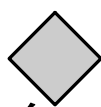
Wuhan Guide Technology Co., Ltd.





告

- (1)在 十分 后 后一 内 器,以 伤;
- (2) 勿使变 器 和 作, 后五分 内 再 ;
- (3) 勿在 下 下变 器 外 印刷 ,以 ;
- (4) 、 作业 , 在关 十分 以后 ;
- (5)变 器 地 子 好 地;
- (6) 不允 变 器内。

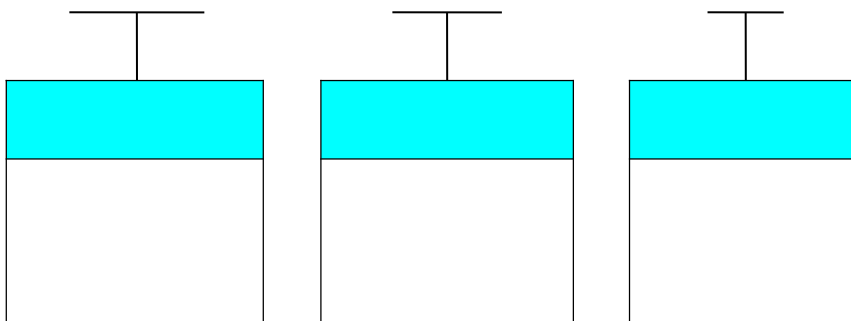


危

- (1)变 器 在 上;
- (2) 列变 器不 于 境, , 向厂 变 器;
- (3) 、 变 器;
- (4)严 交 到变 器 出 U、V、W上;
- (5)变 器在 中, 勿 作业。



- a. 型， 型不 可 会 变 器 坏。
b. 不 任何 坏 件 变 器，否则 受伤 危 。



客

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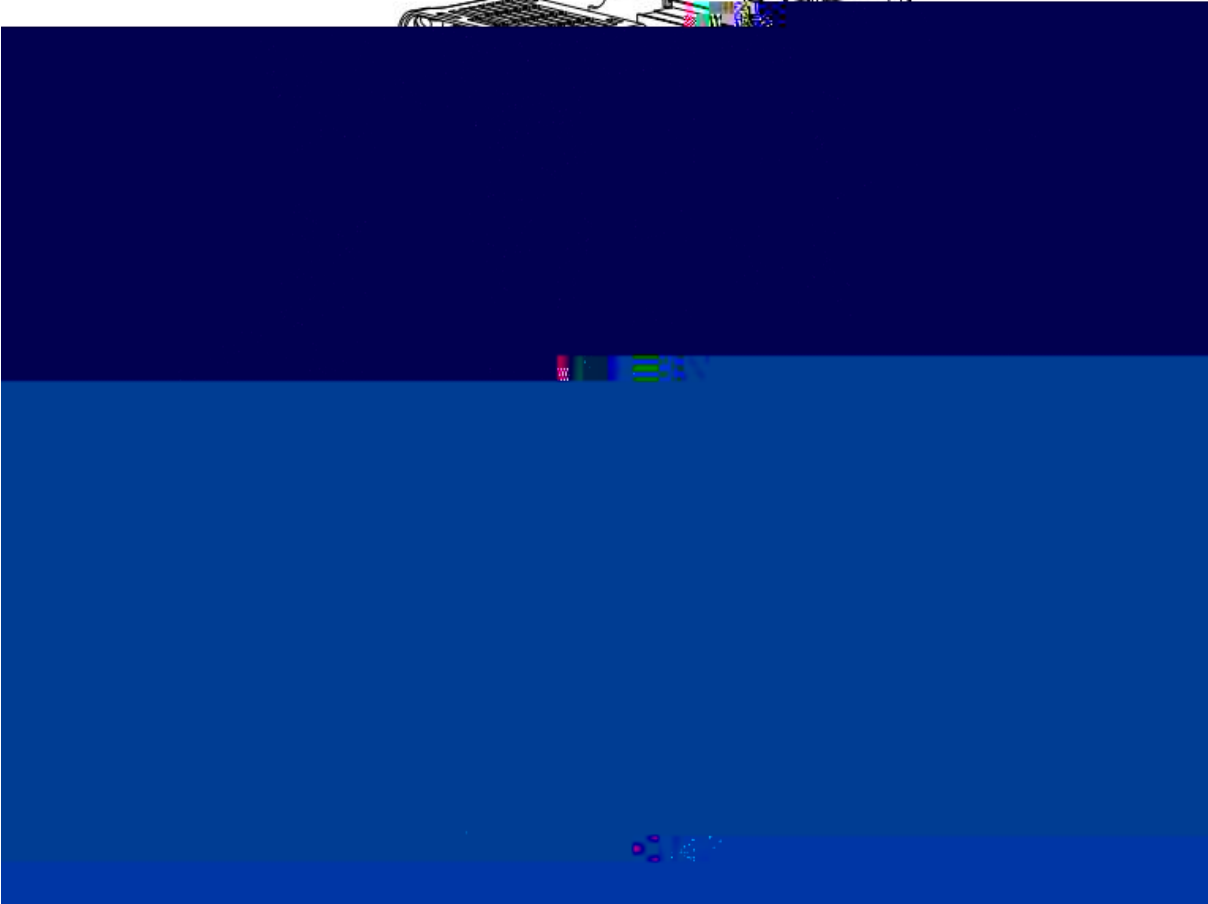
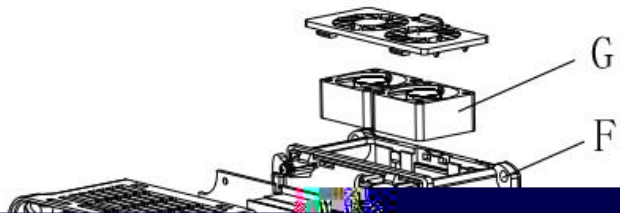
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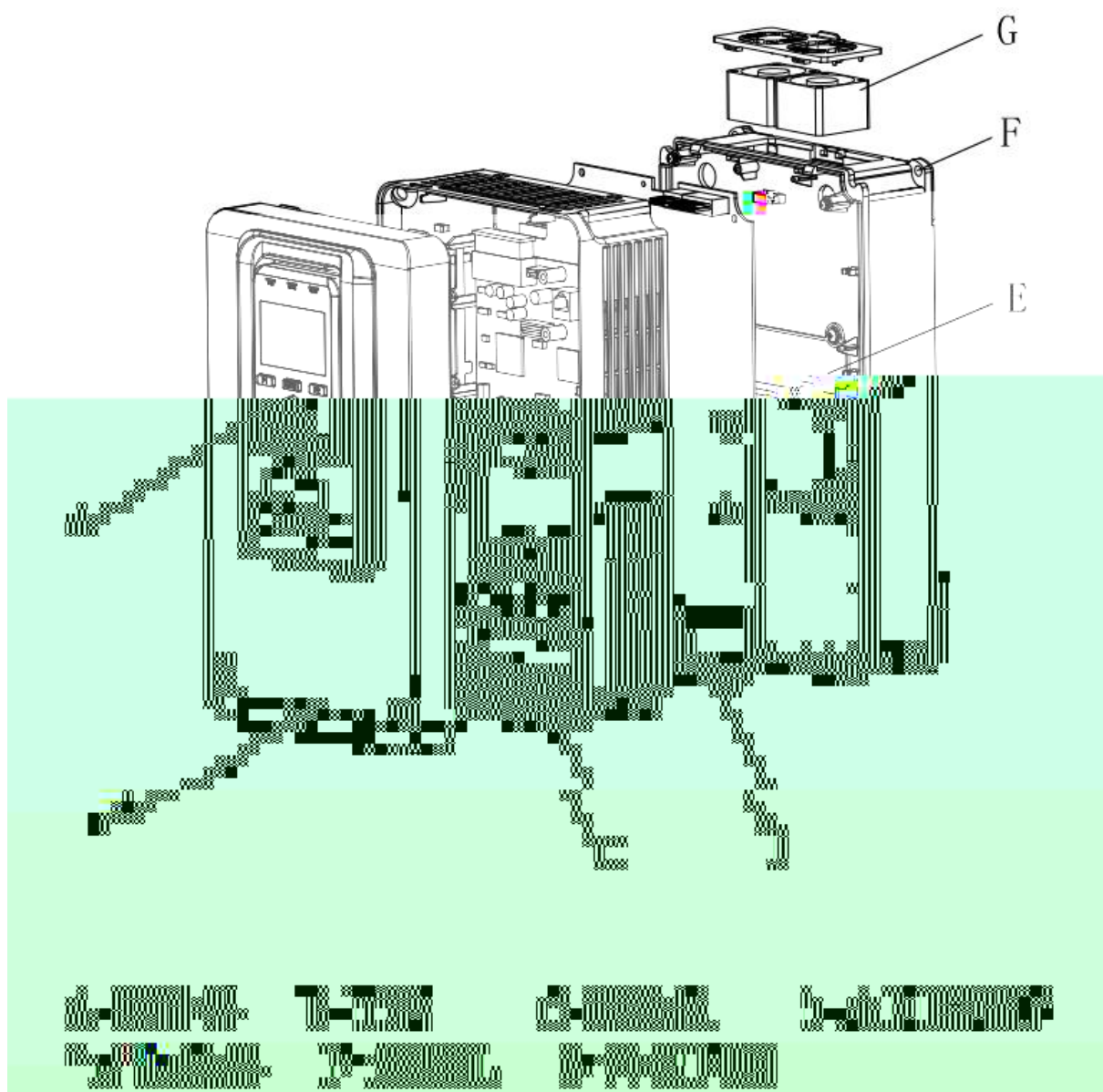
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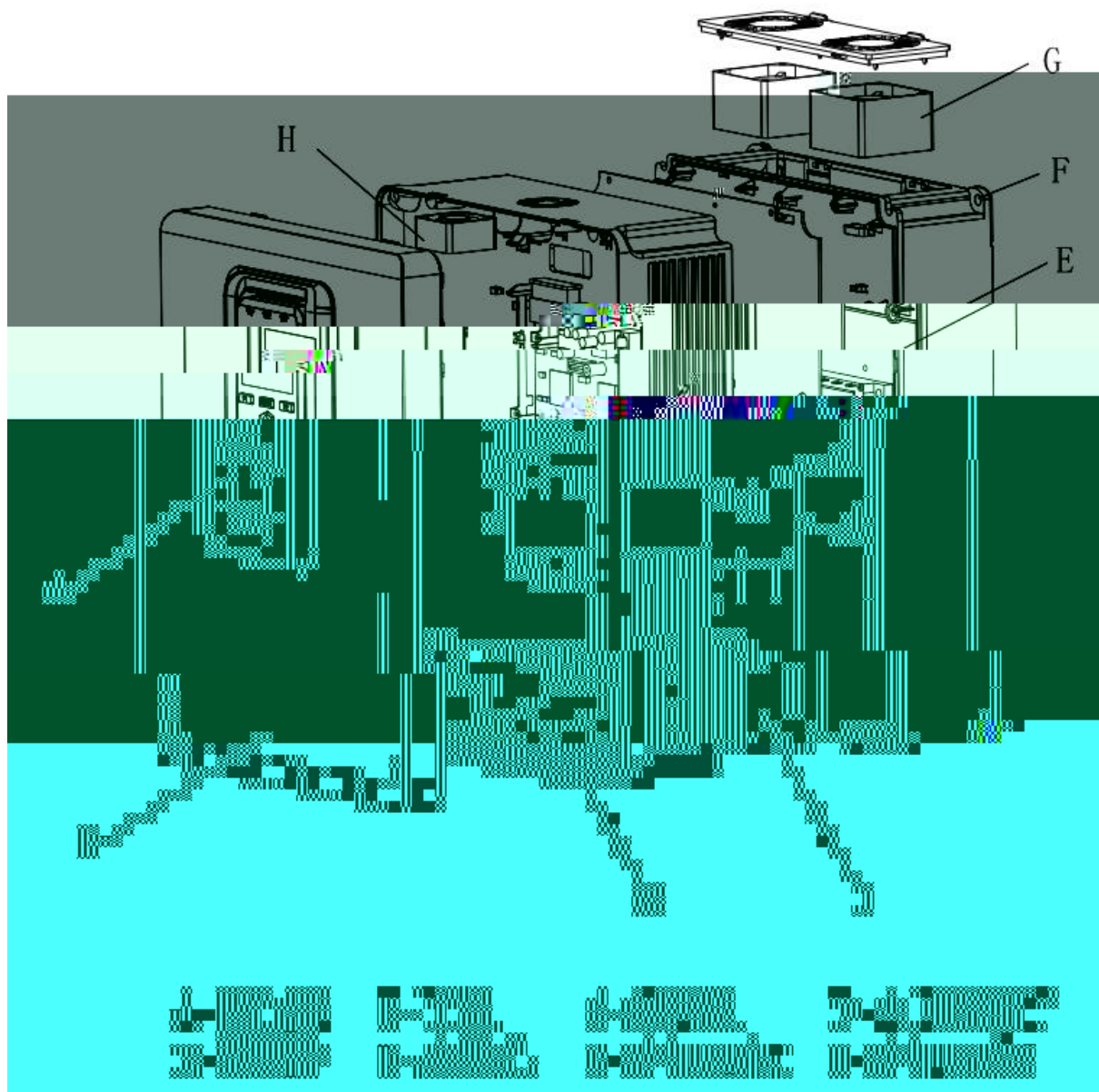


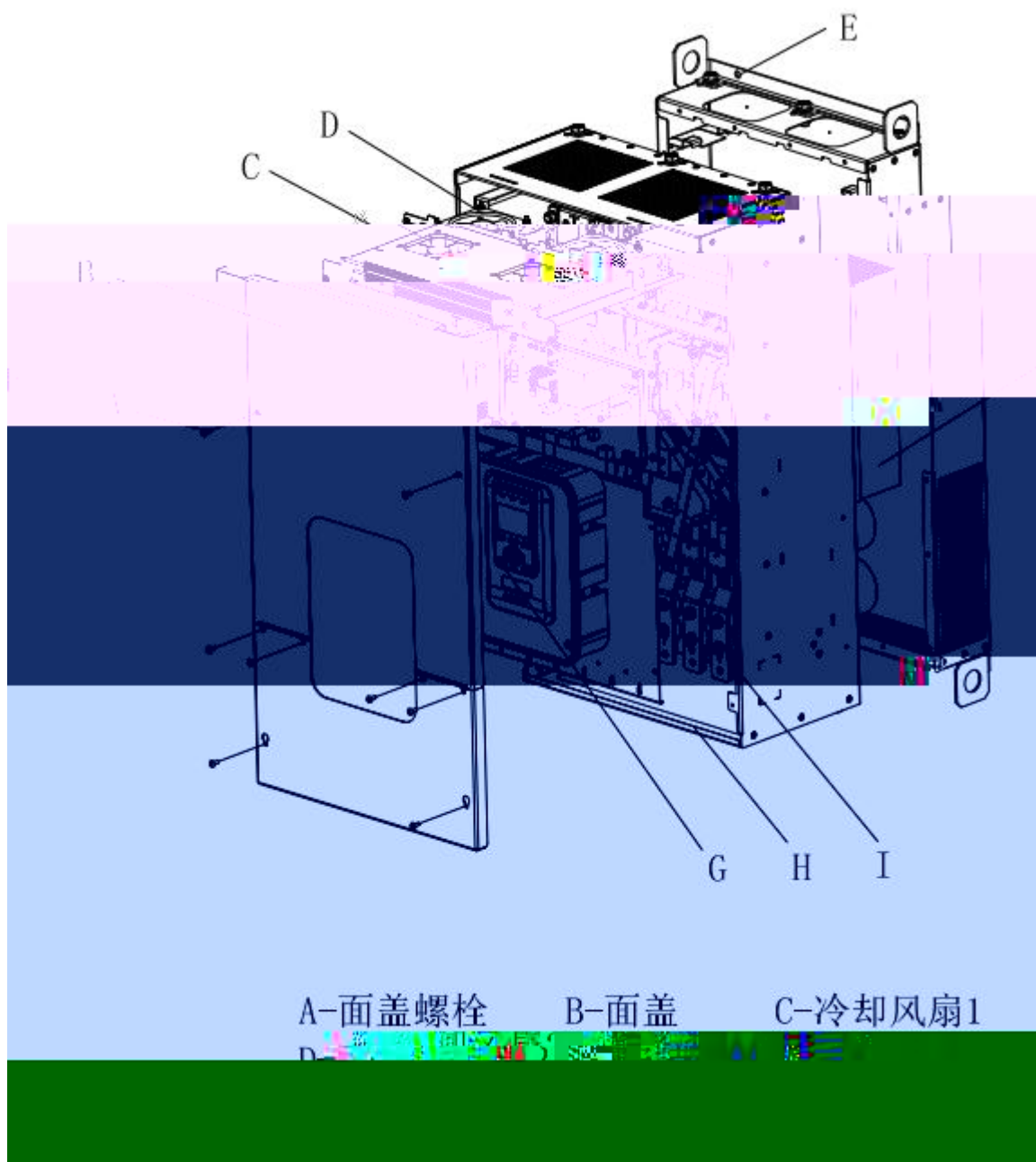
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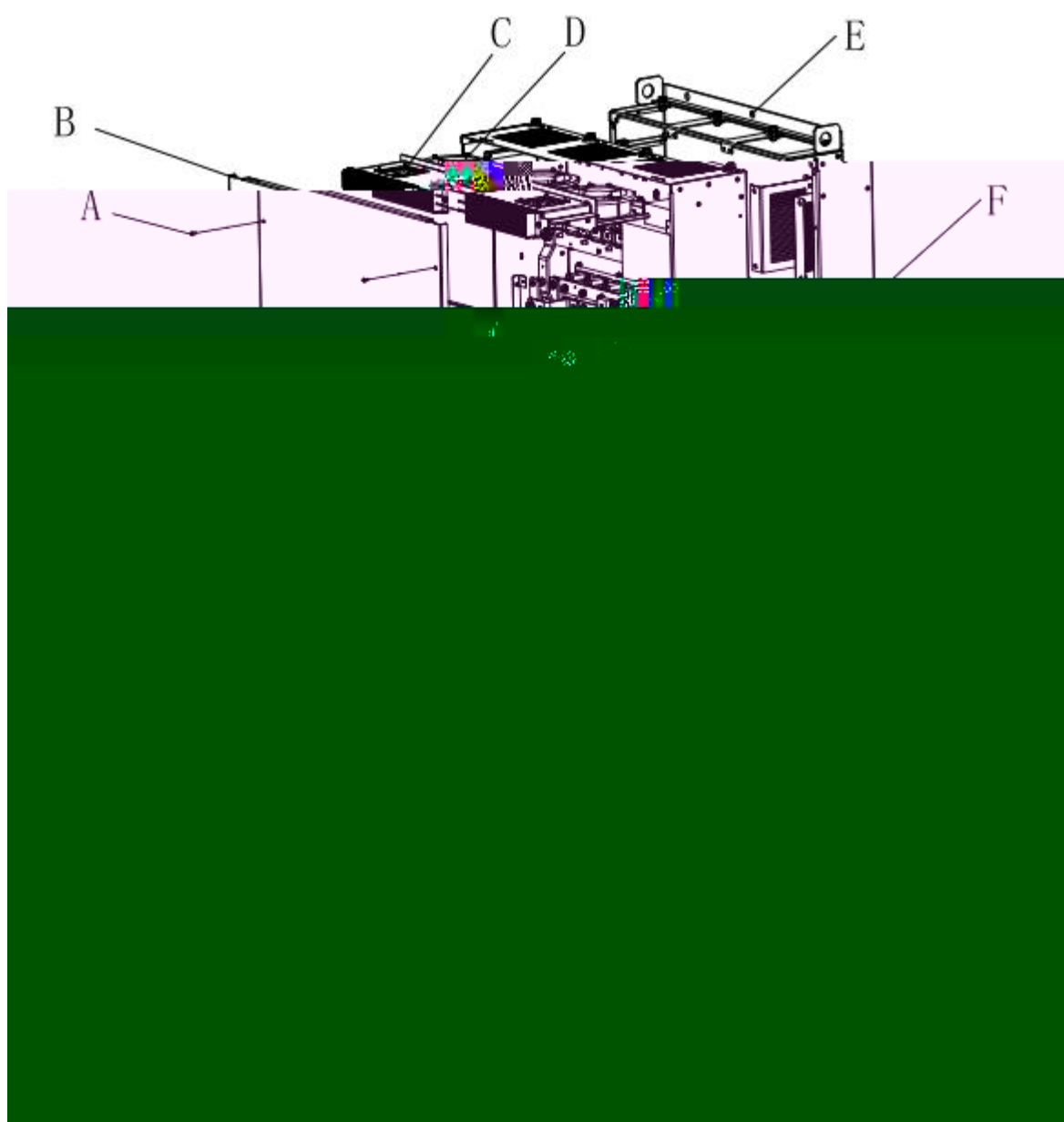
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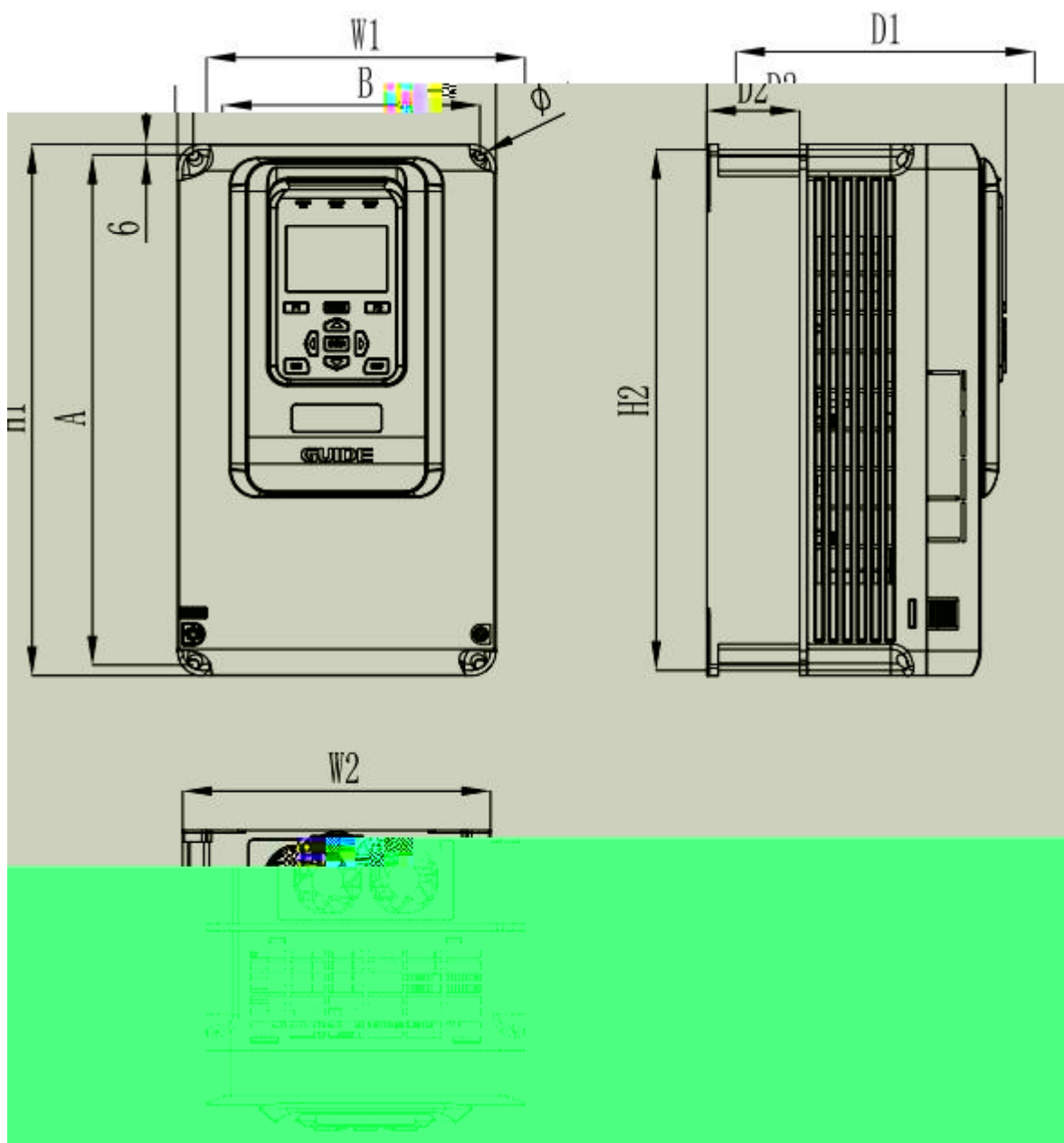


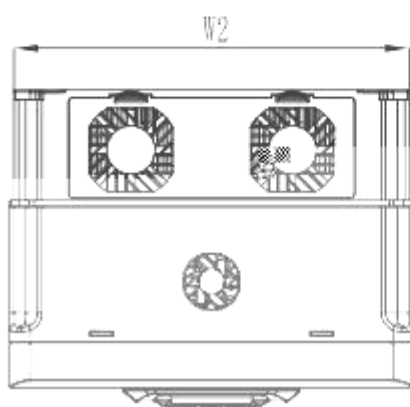
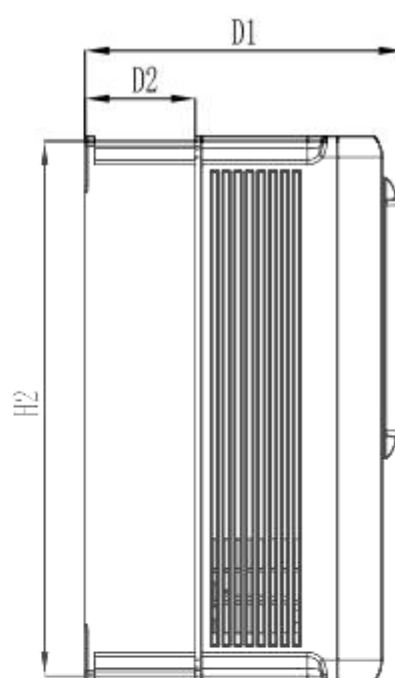
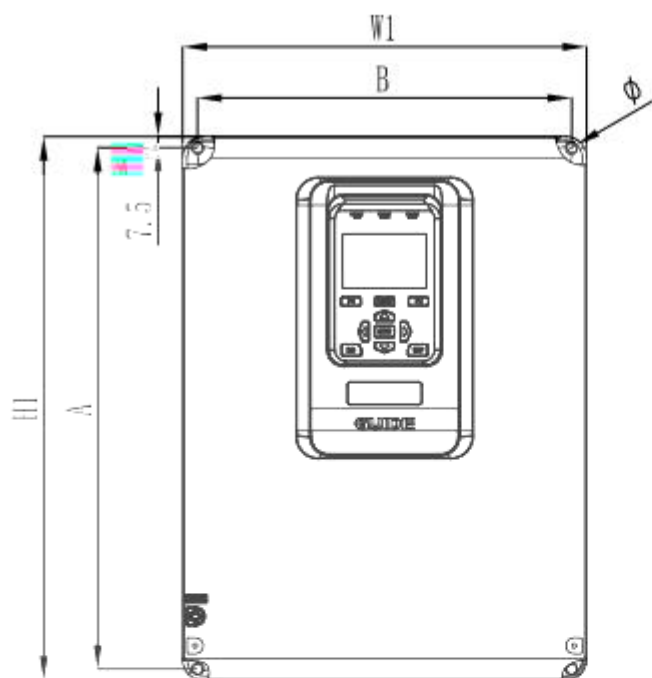


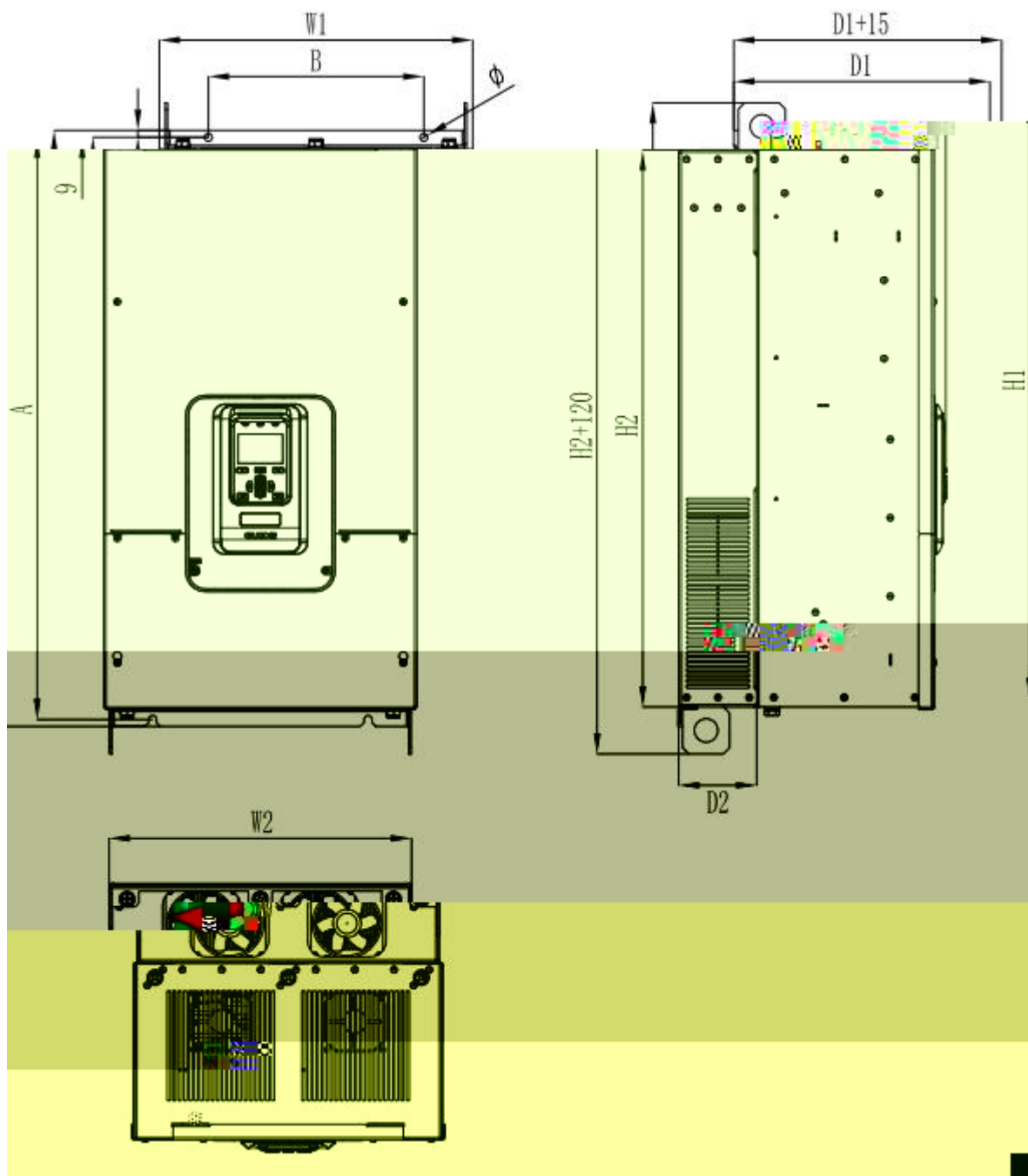


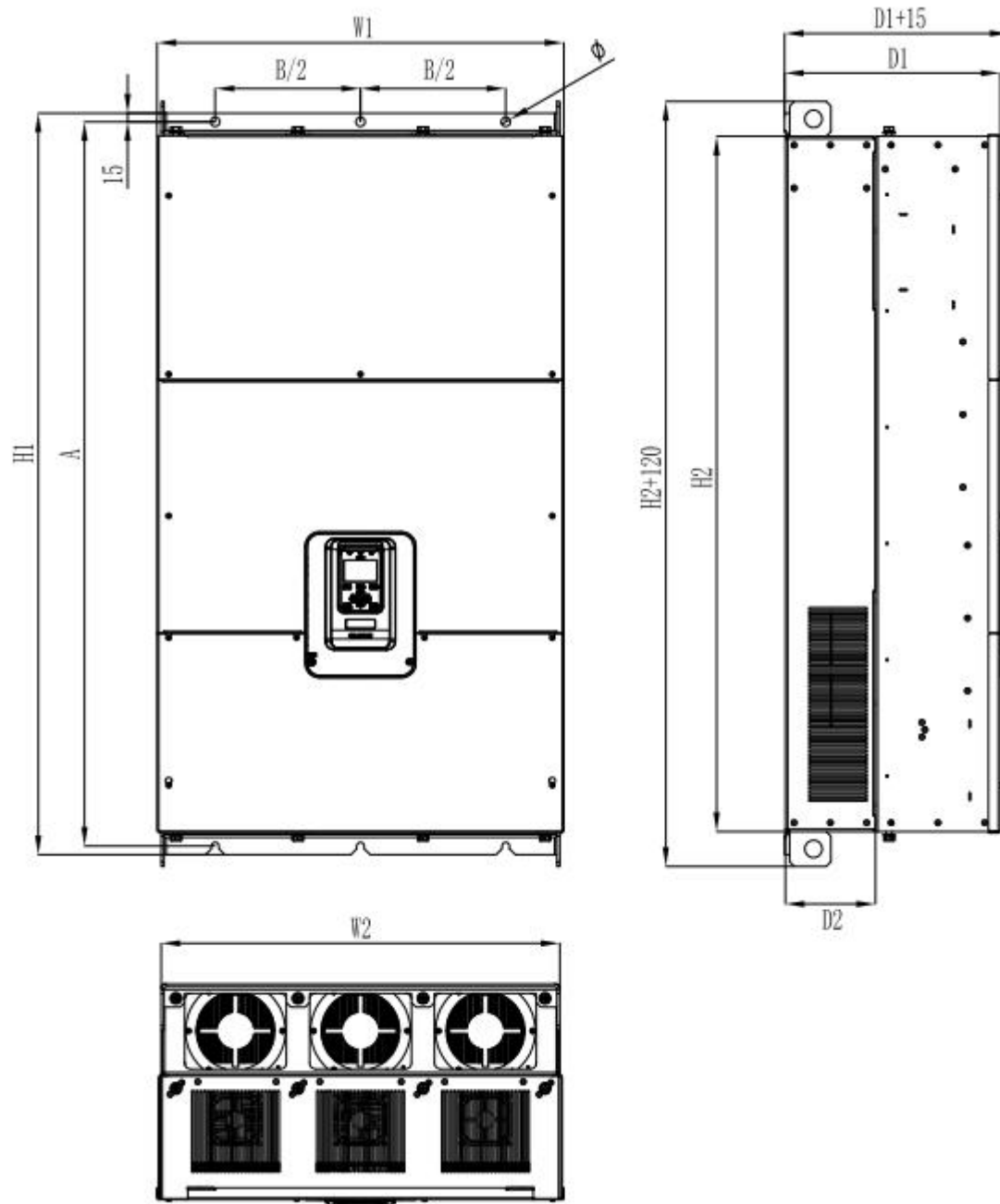






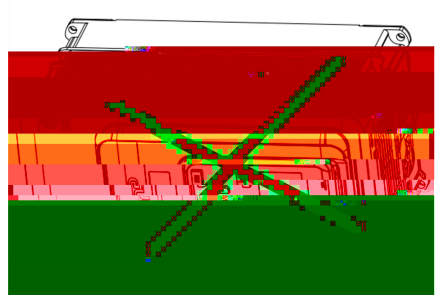
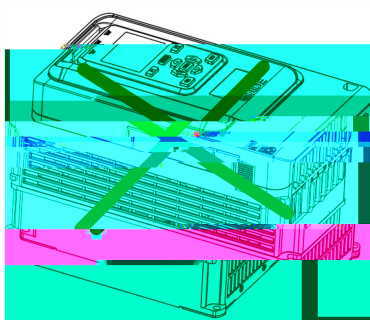
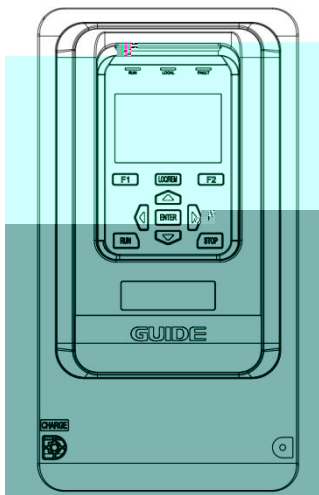


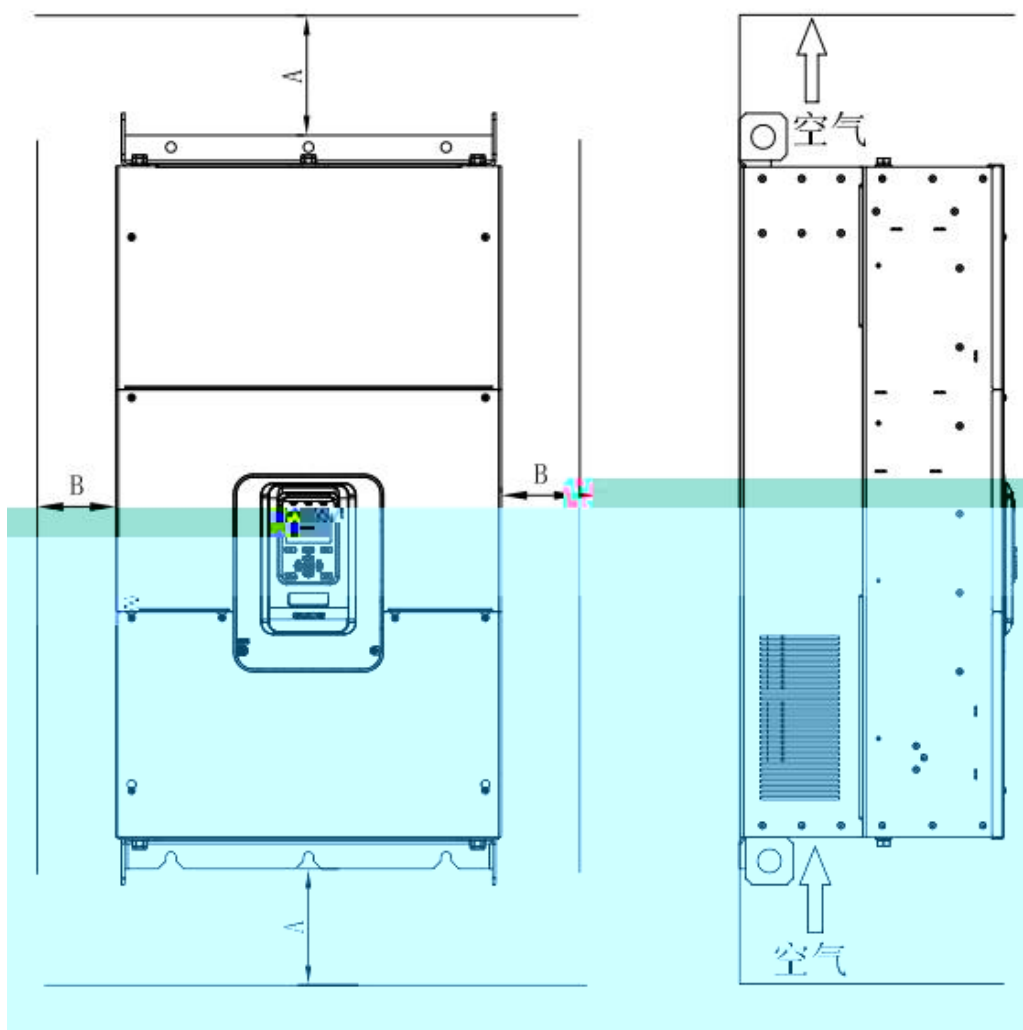


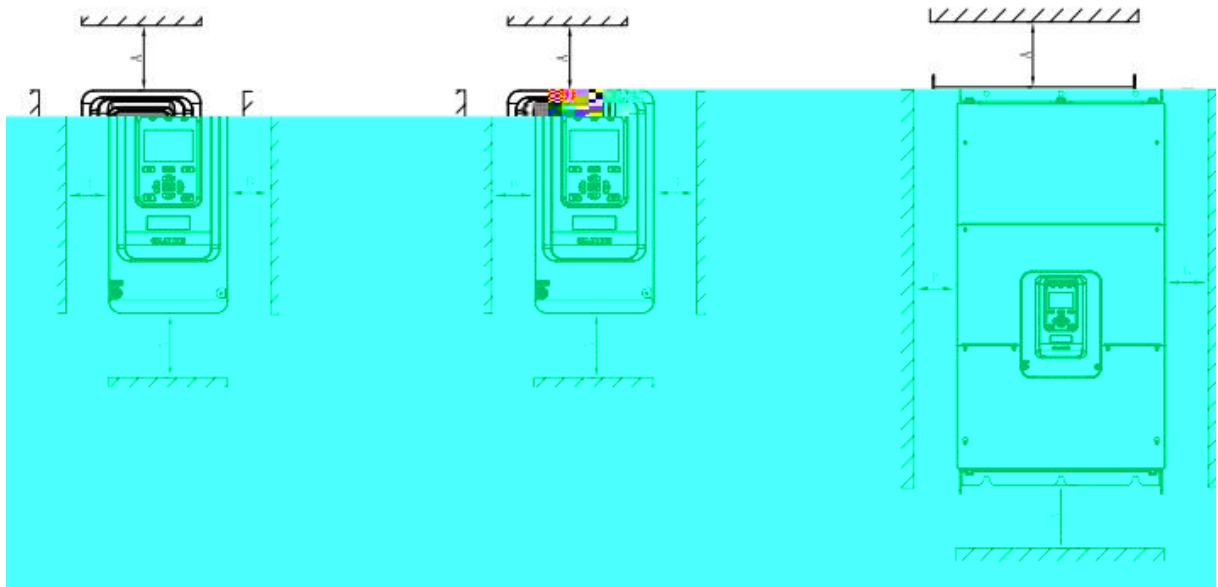


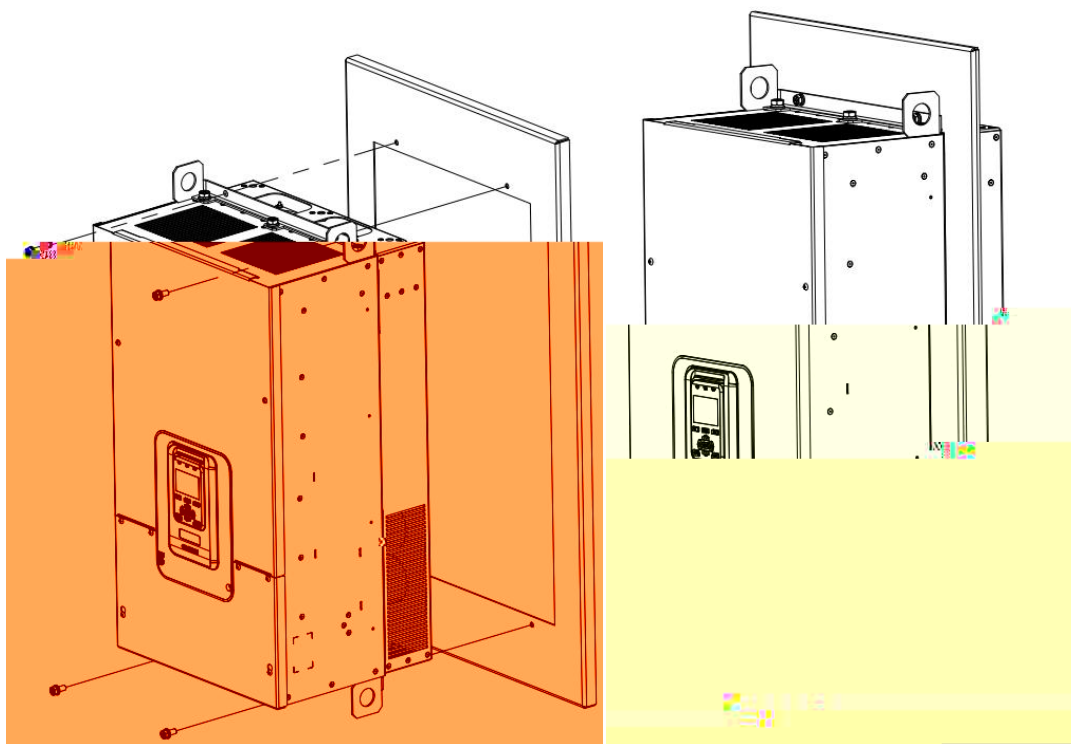
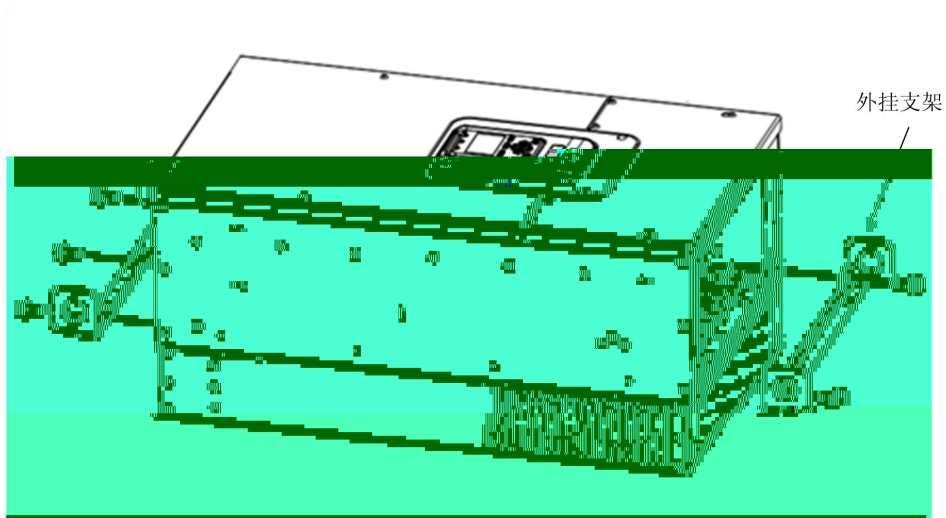
	
	

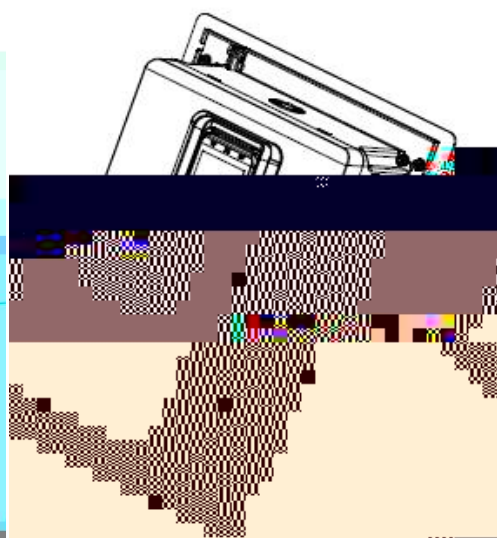
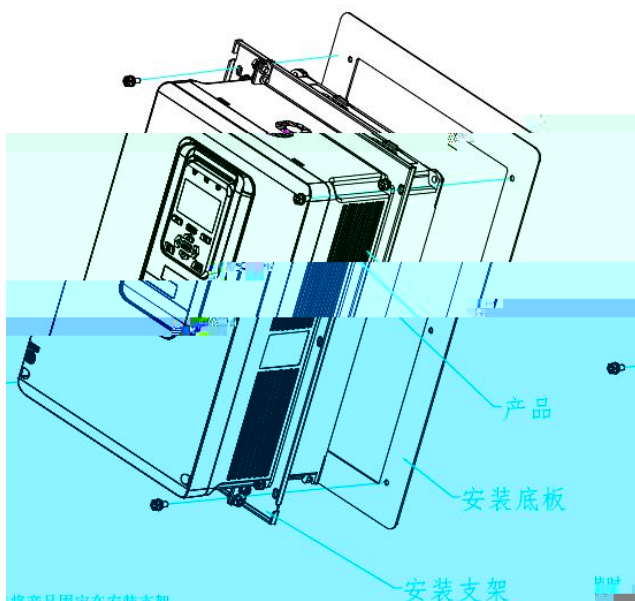


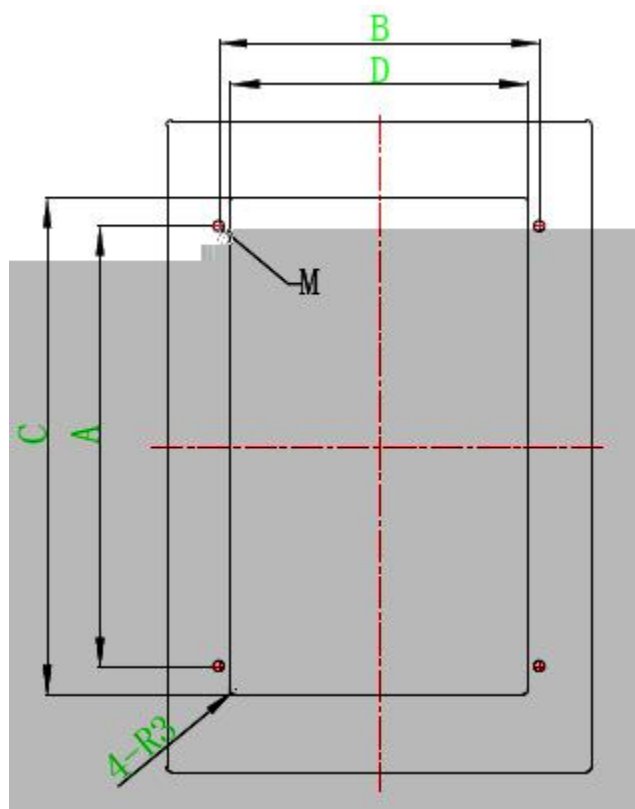
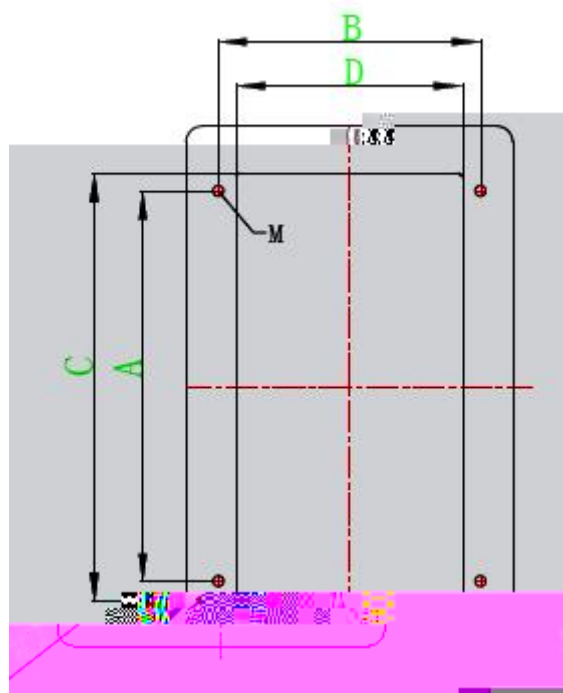


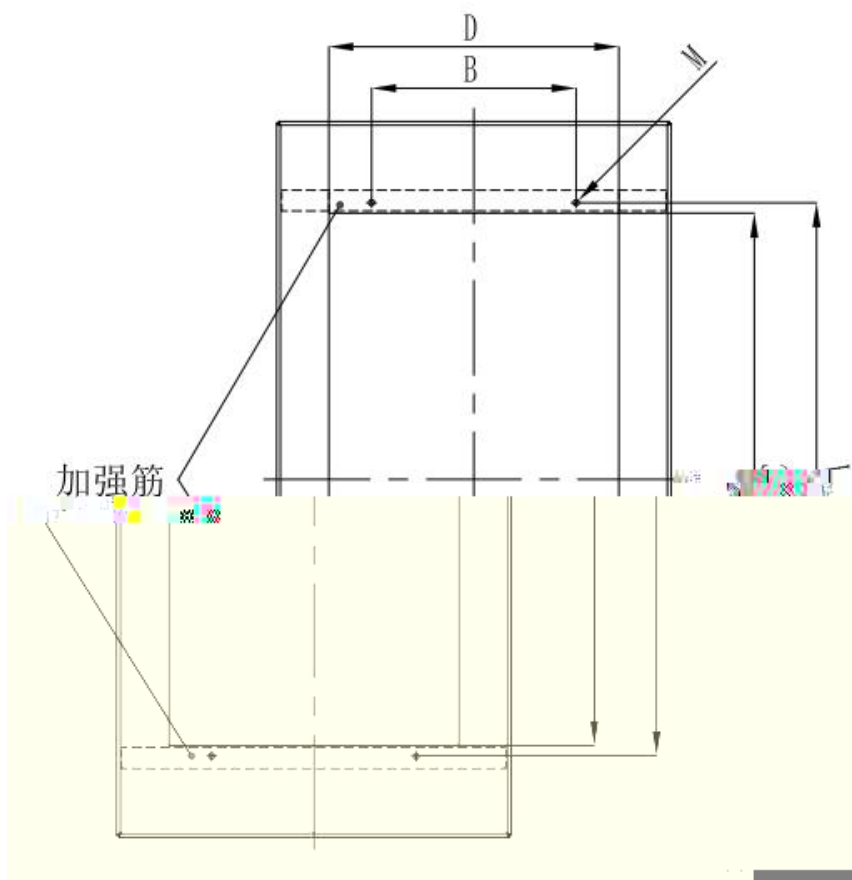
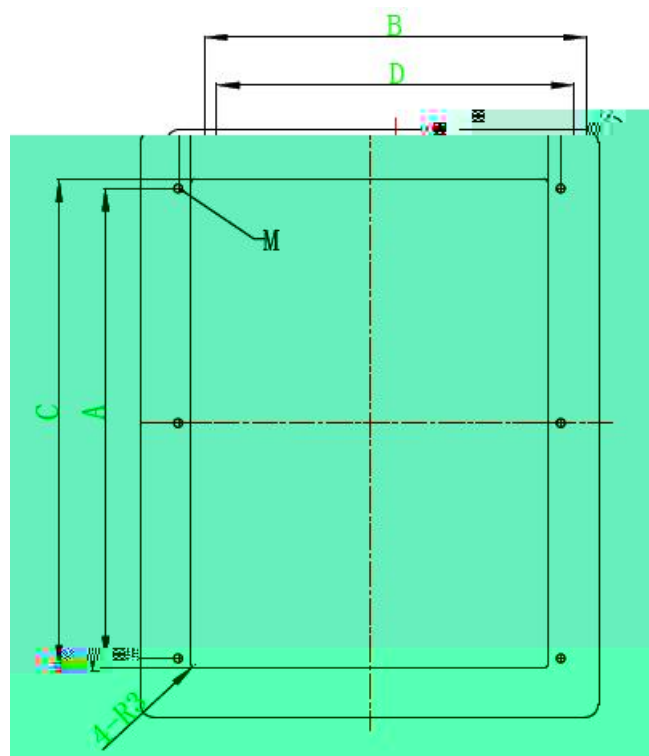


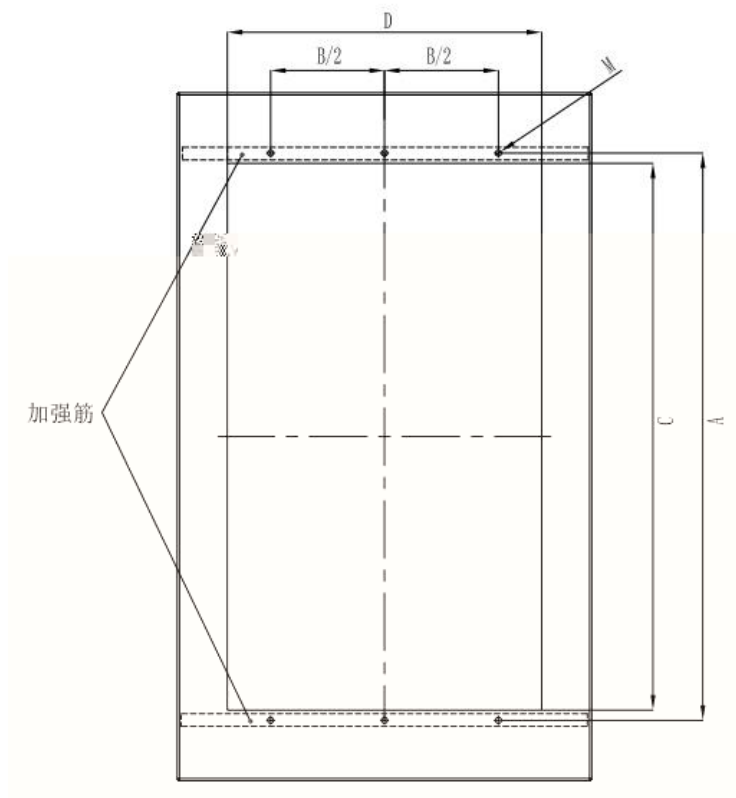




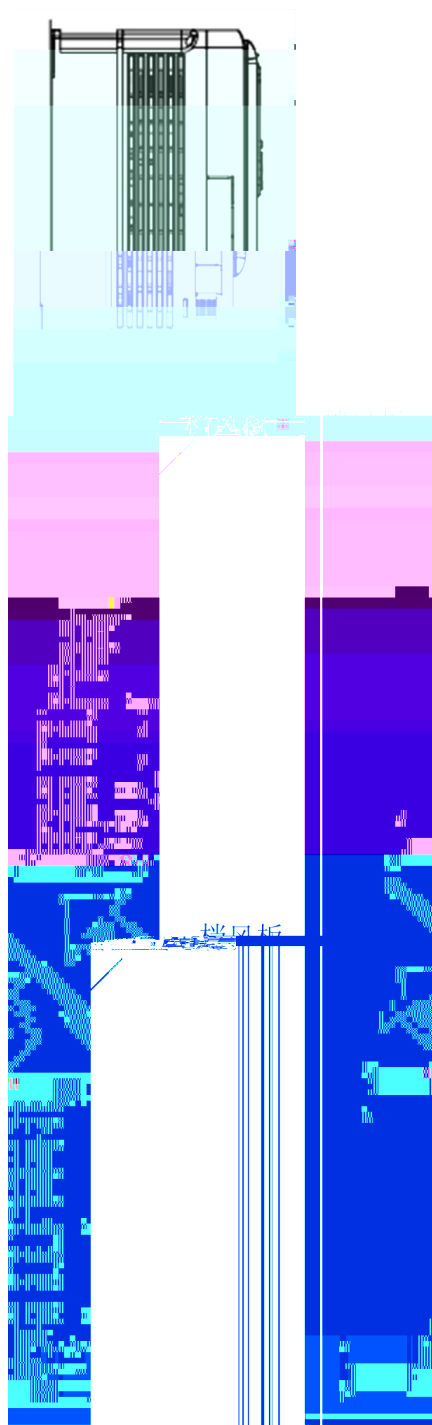


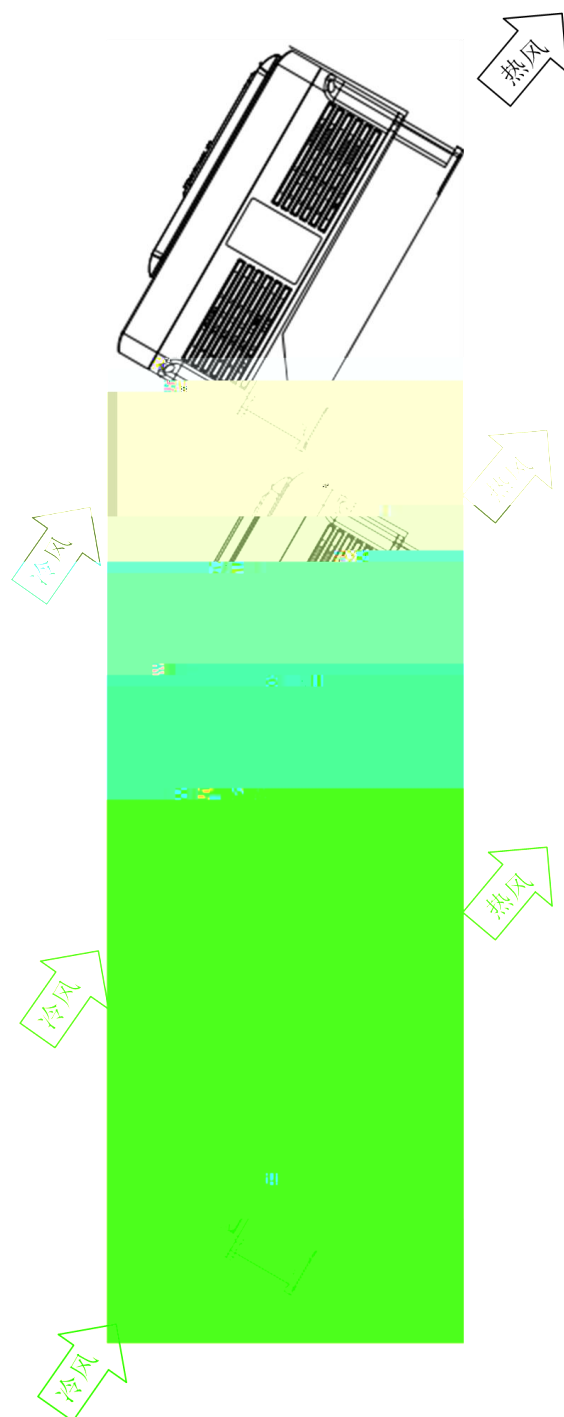


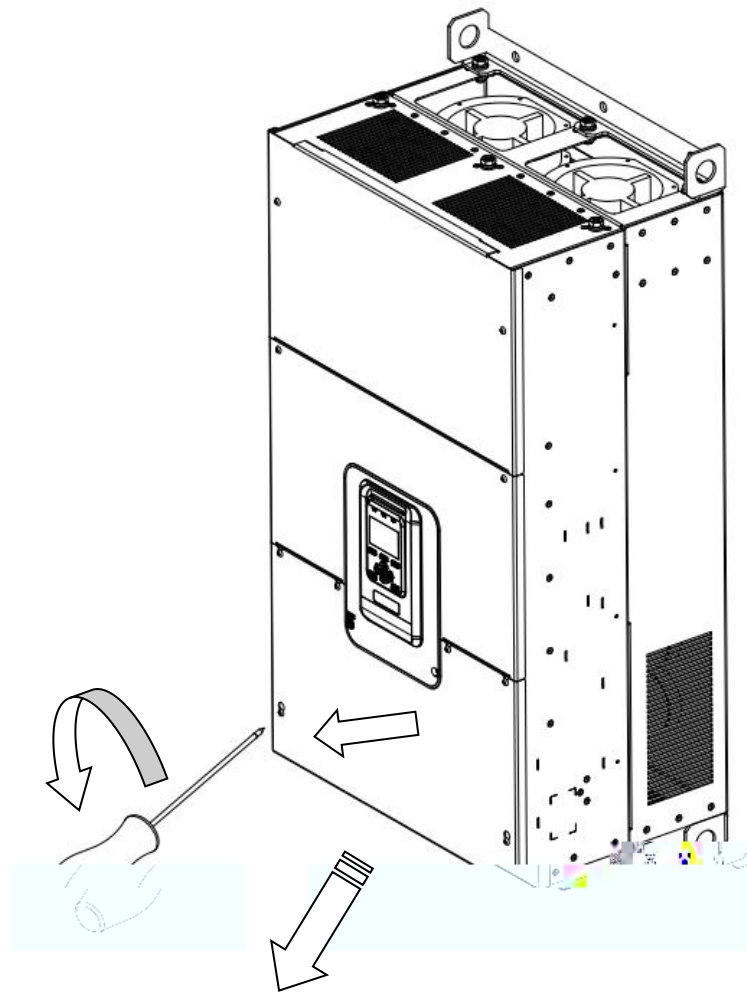


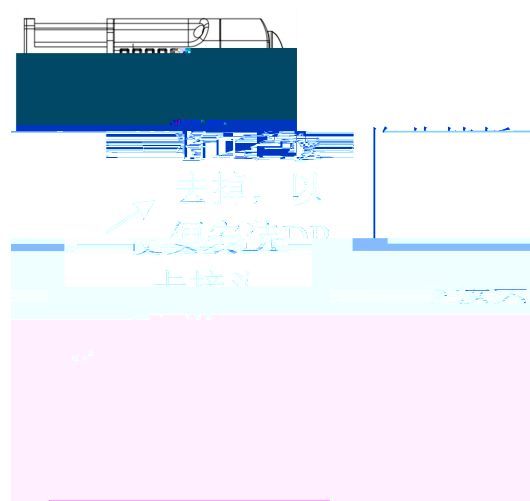
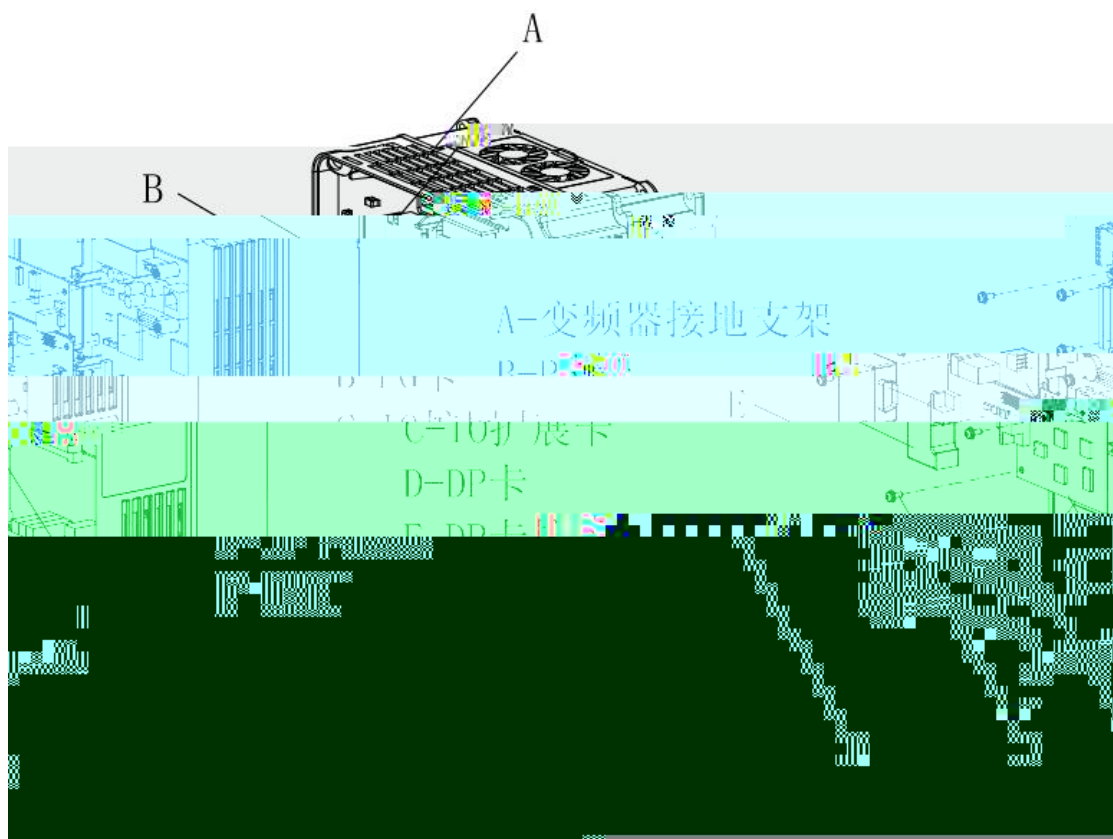


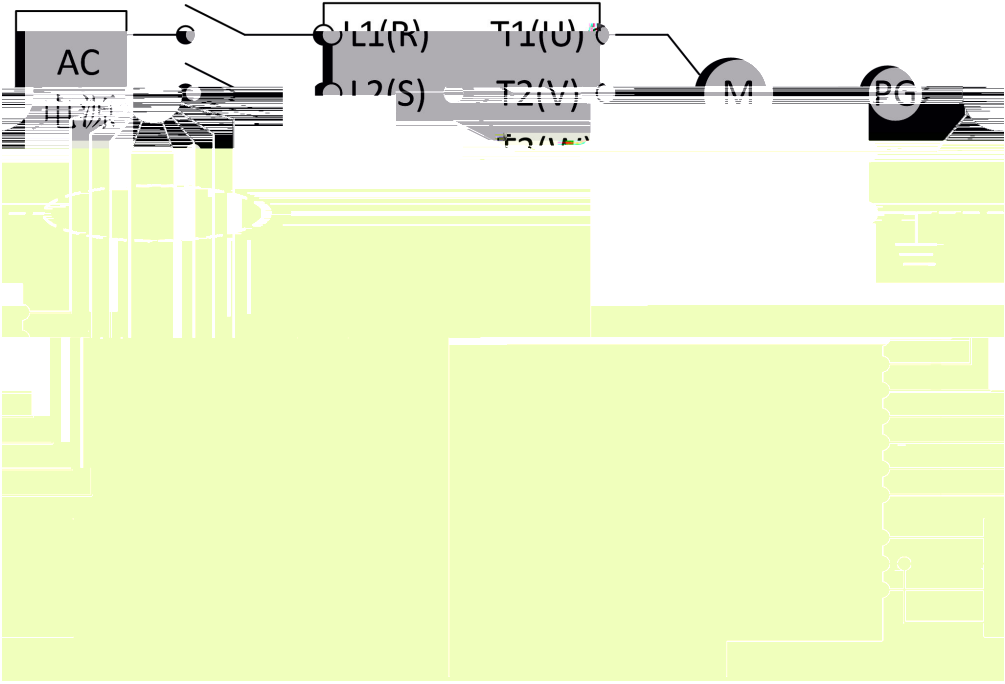


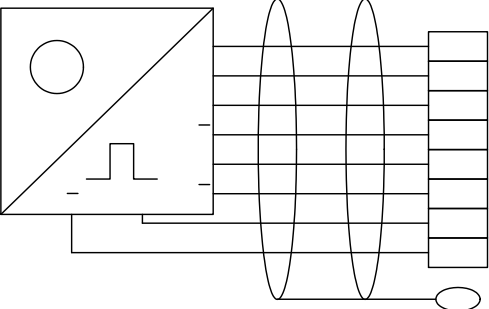


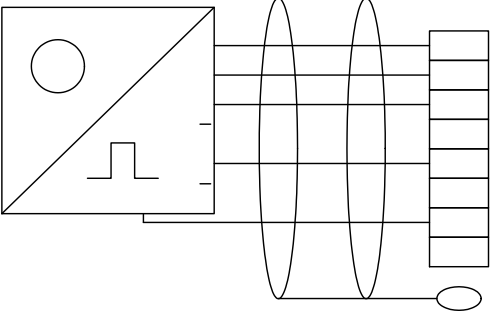


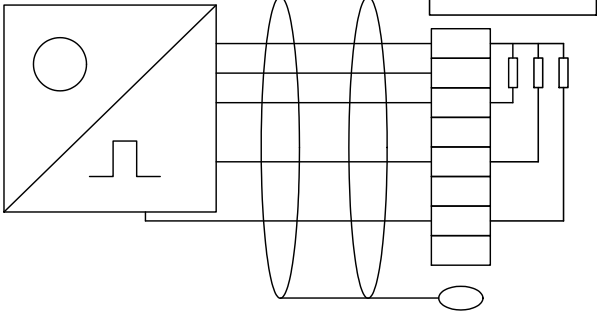


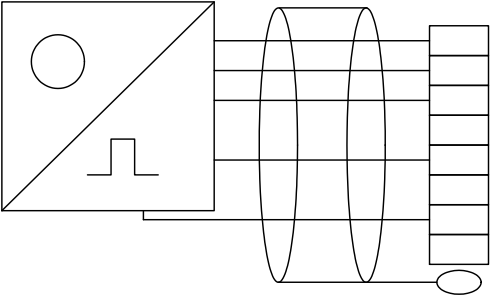


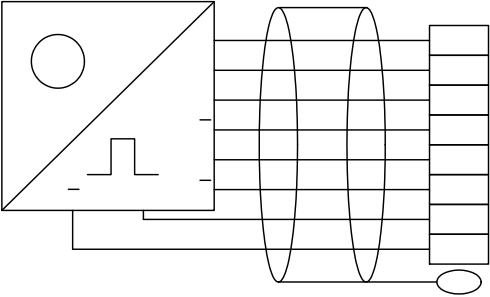


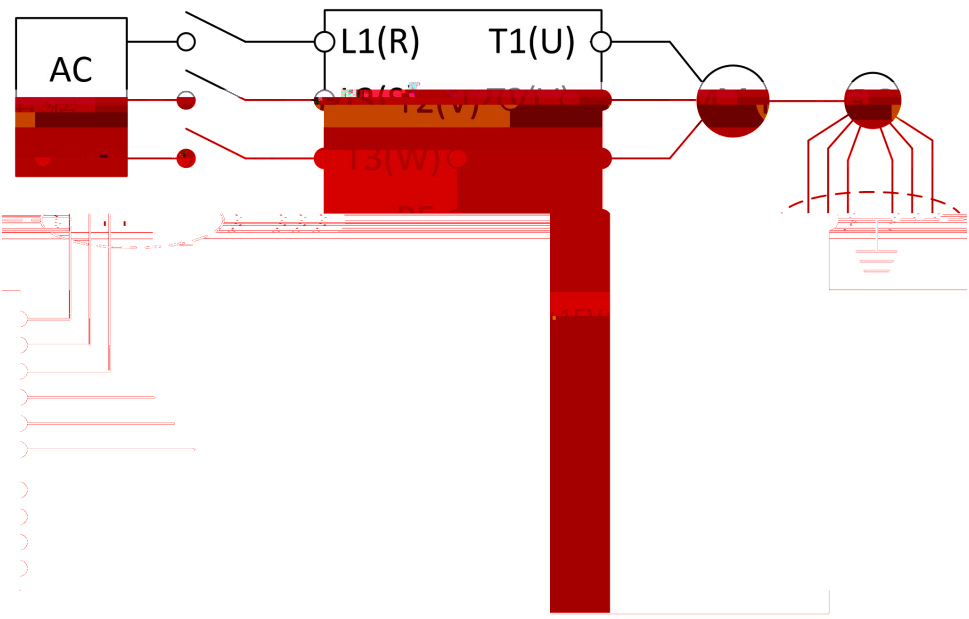
			

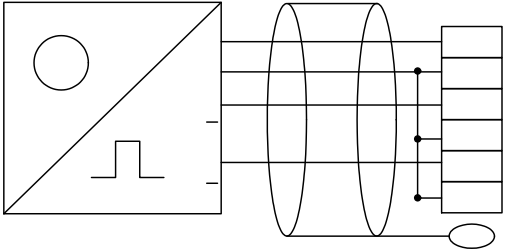
		

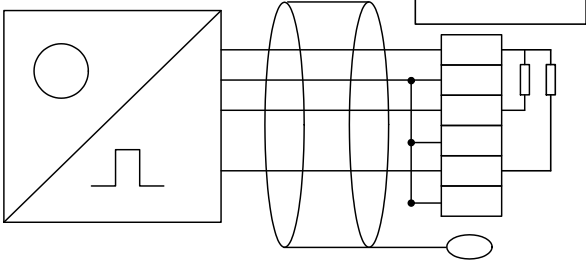
		



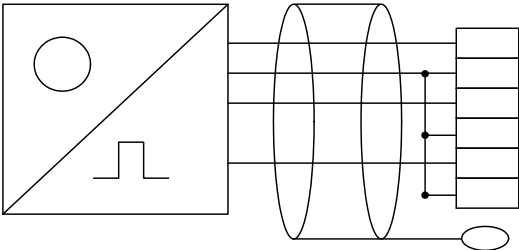




A diagram of a camera lens system. On the left is a square sensor with a circle in the top-left and a step-like shape in the bottom-right. Two lenses are in the center. On the right is a film plane with a vertical line of dots and a small circle below it.

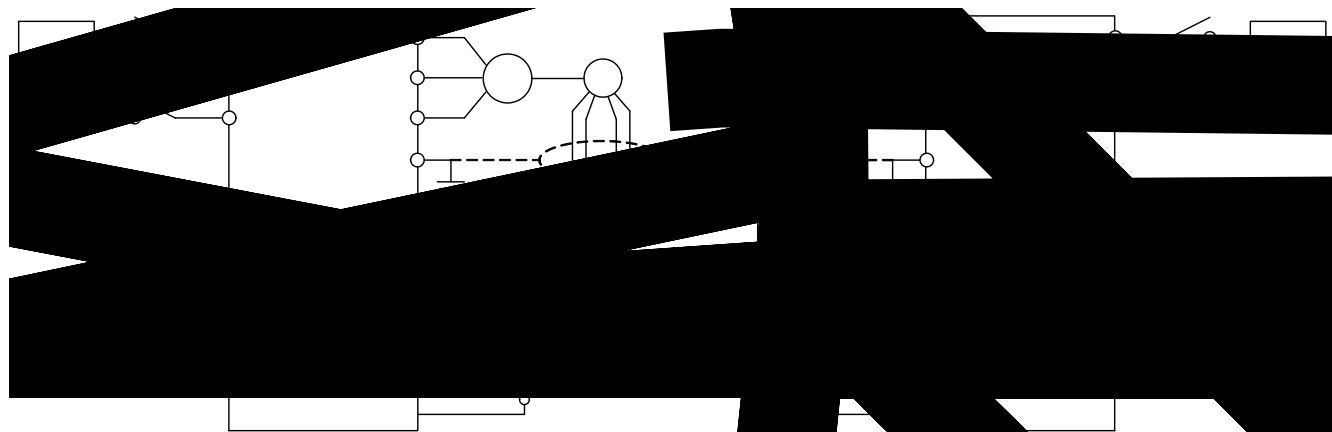
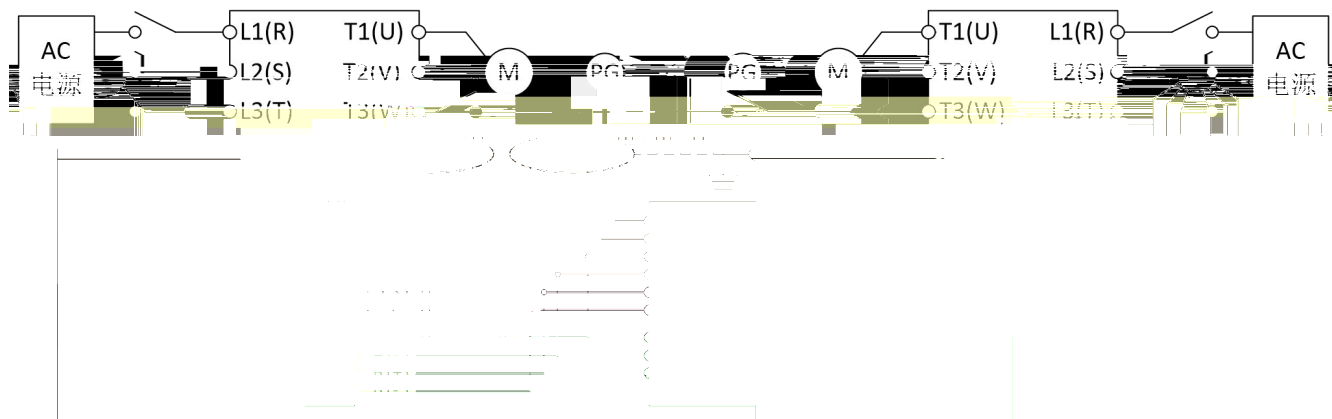


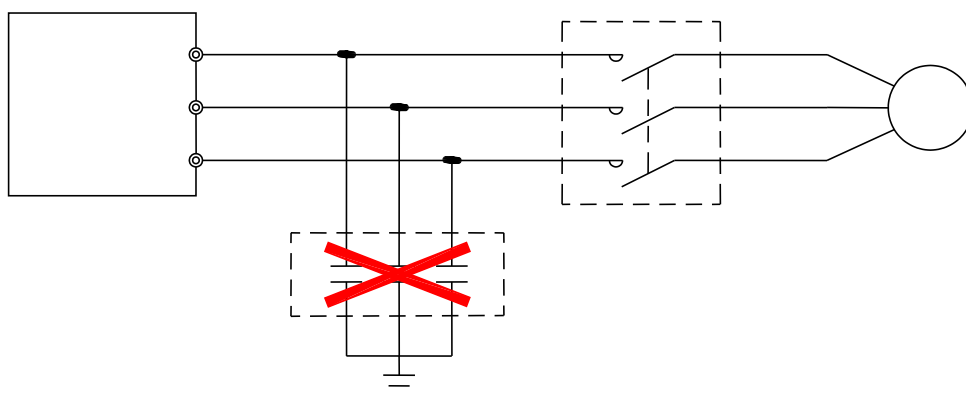
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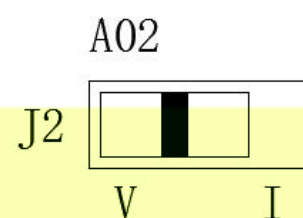
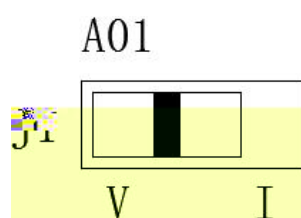
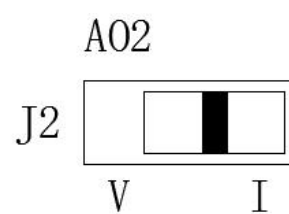
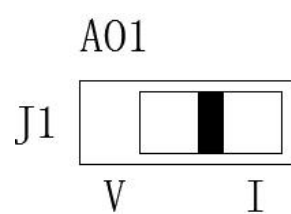


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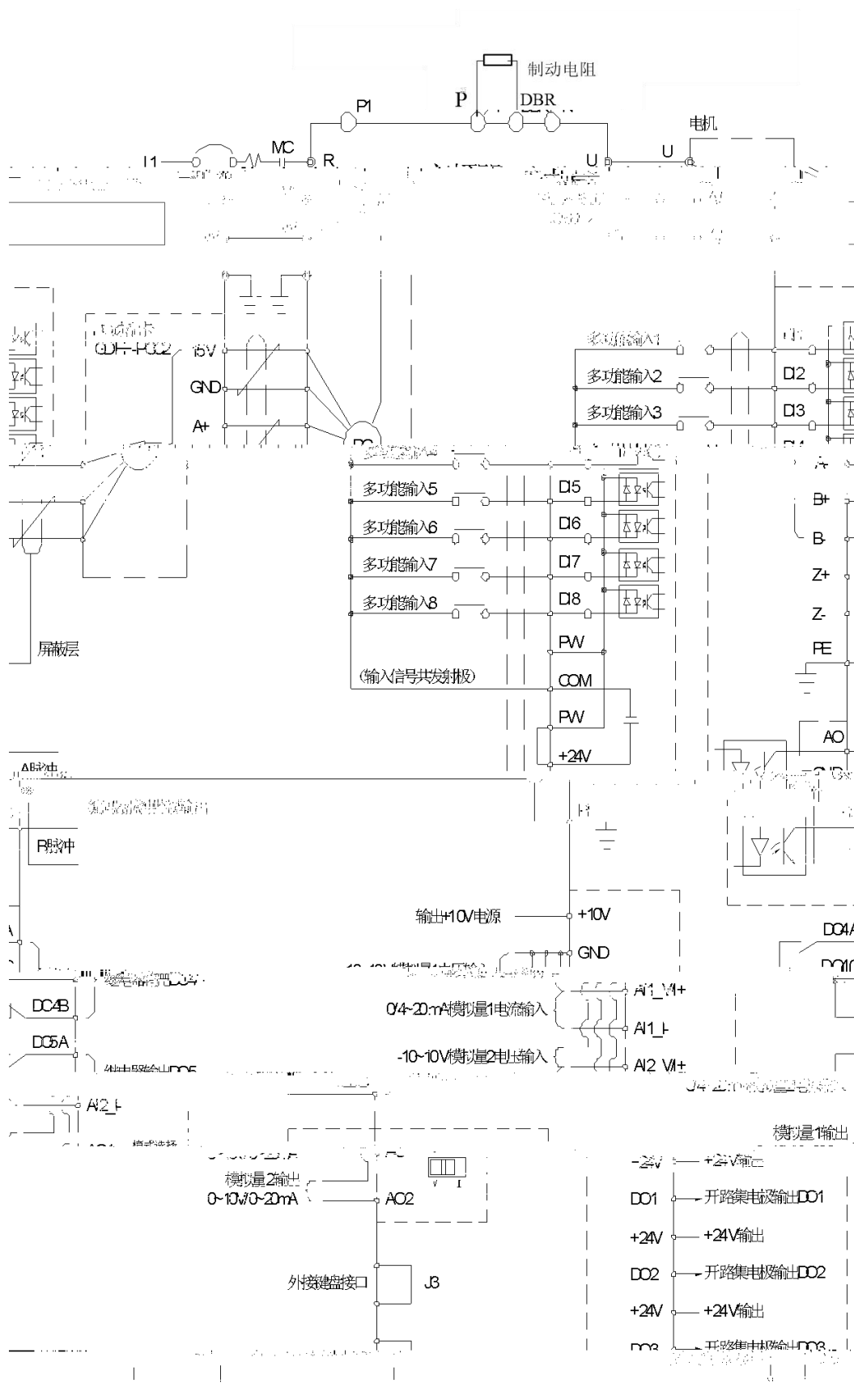


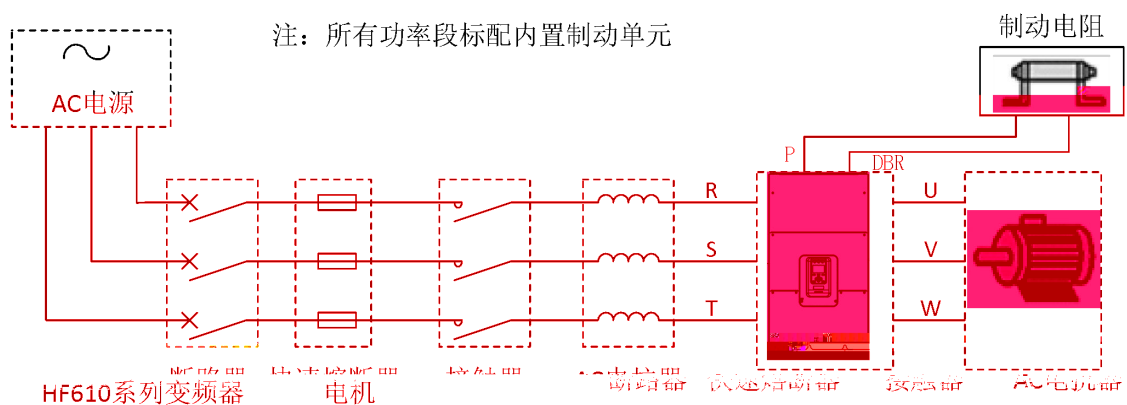








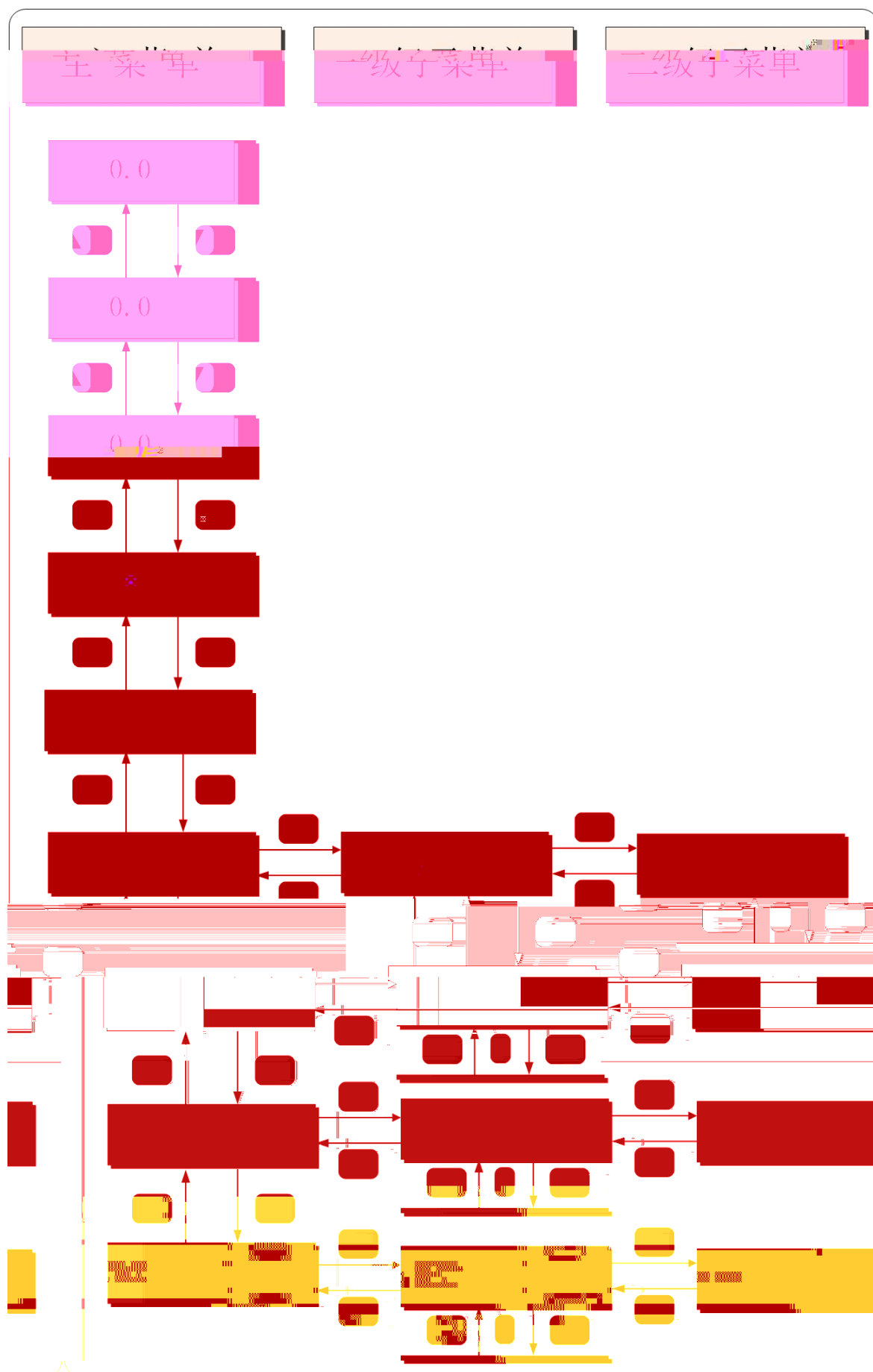




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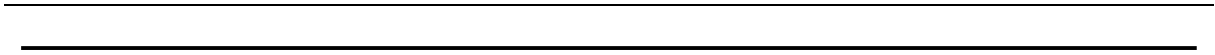




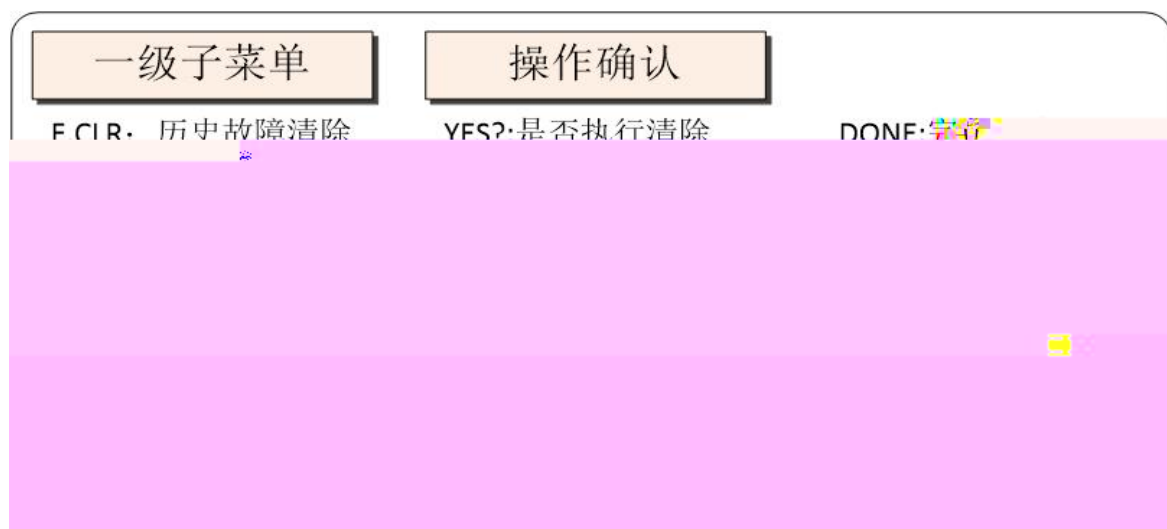
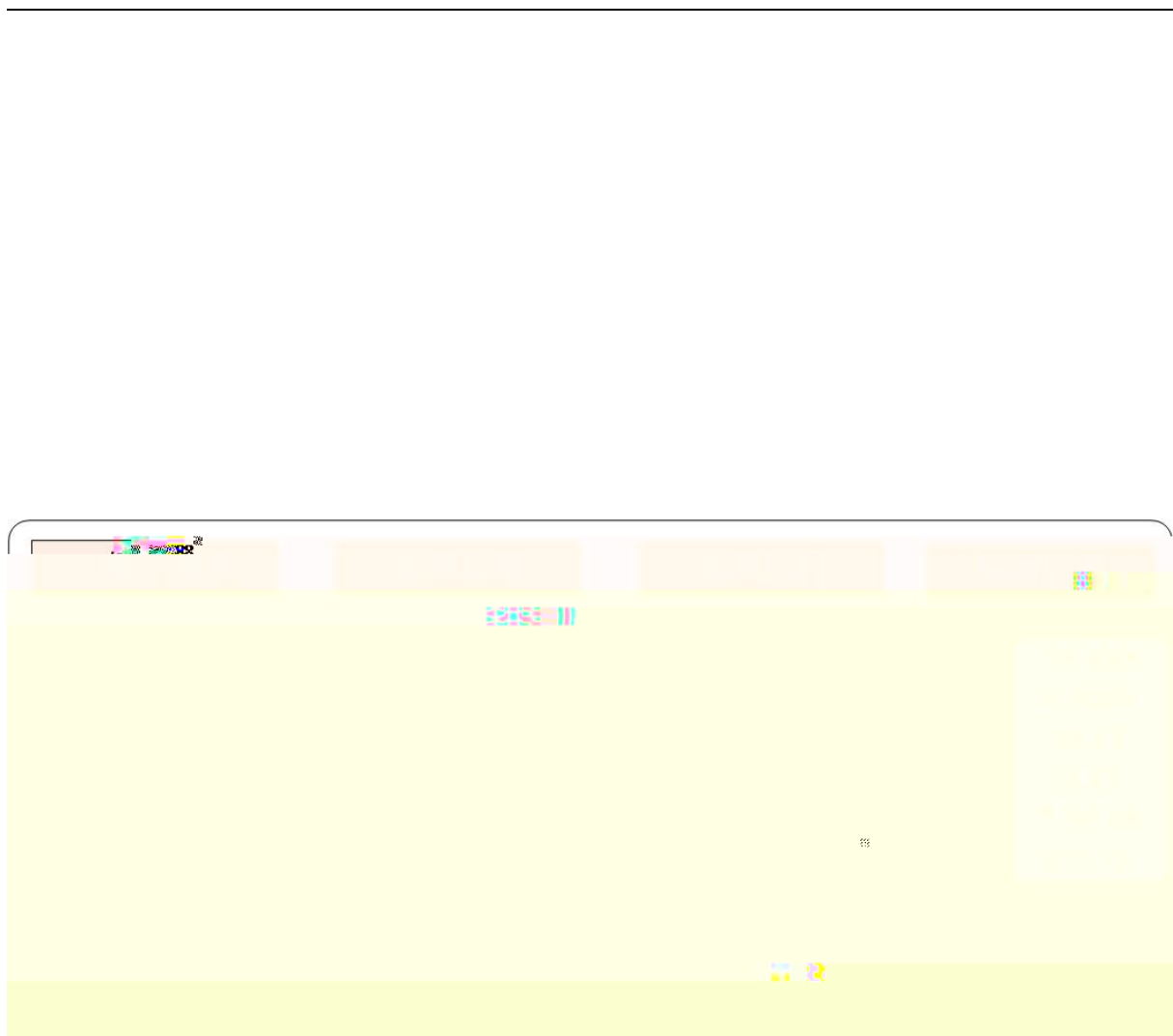


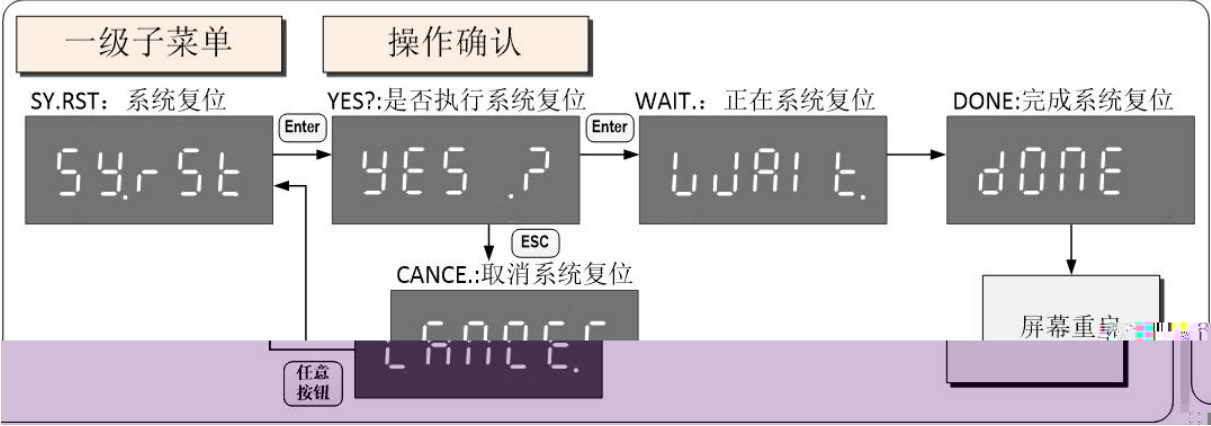


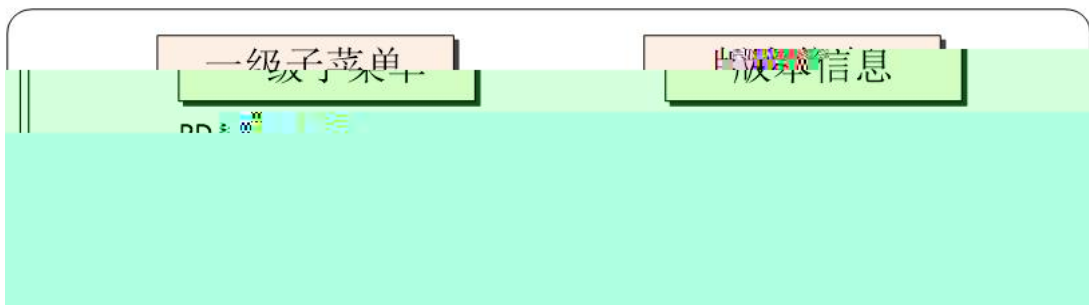
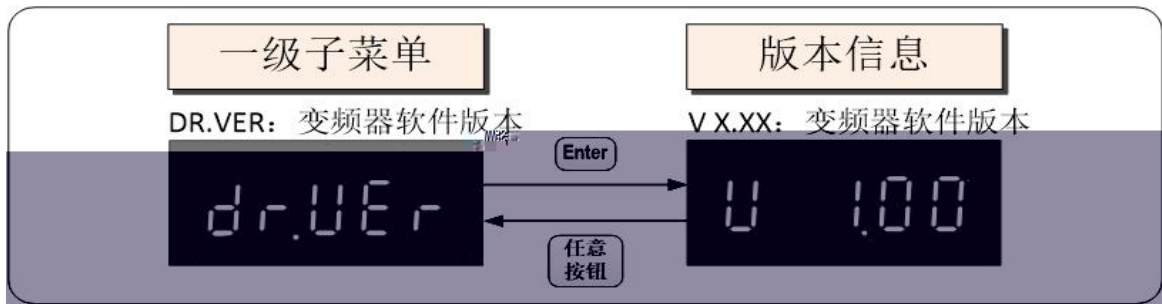
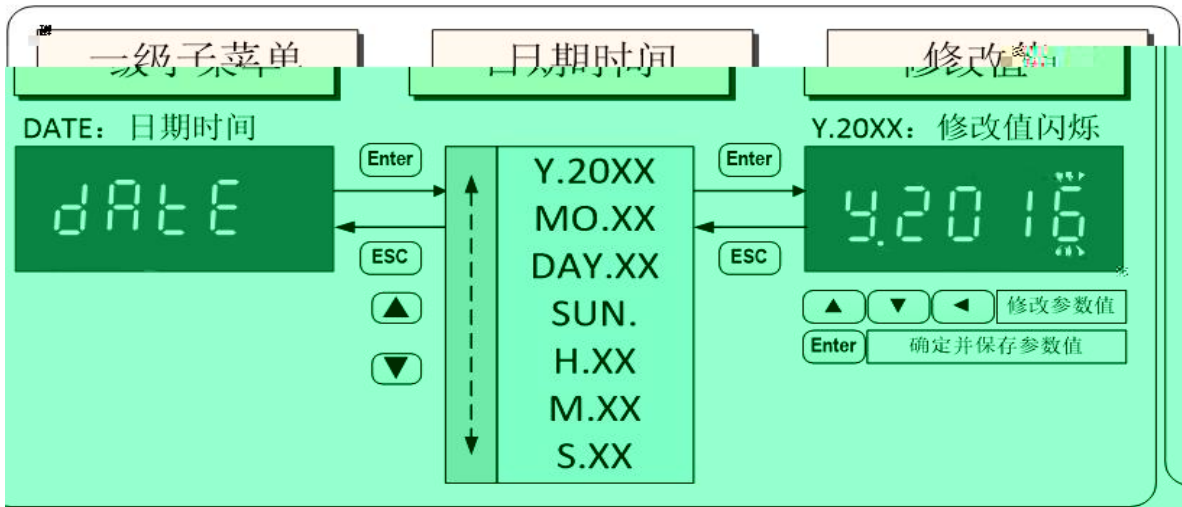


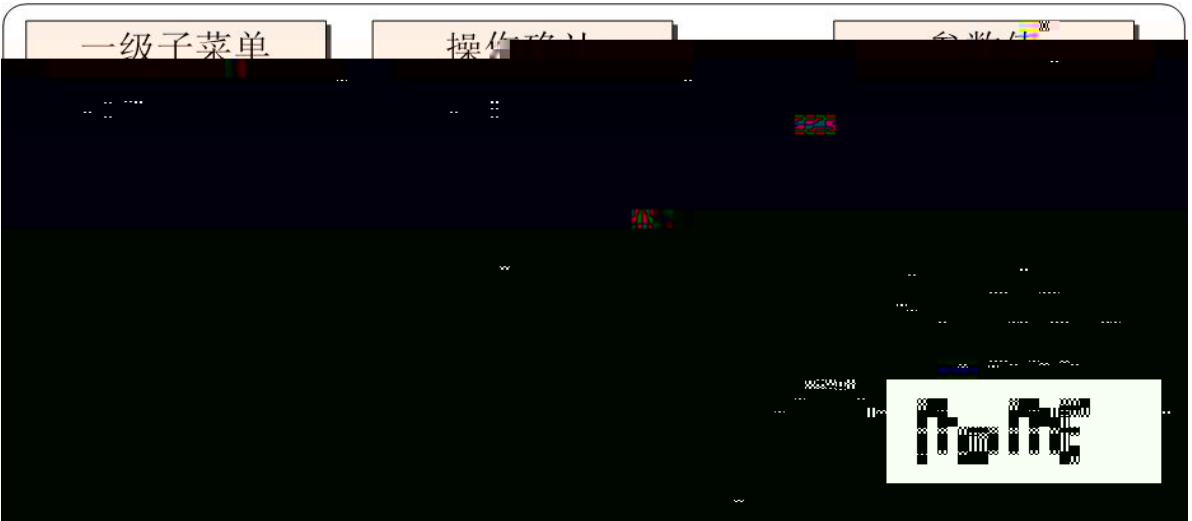




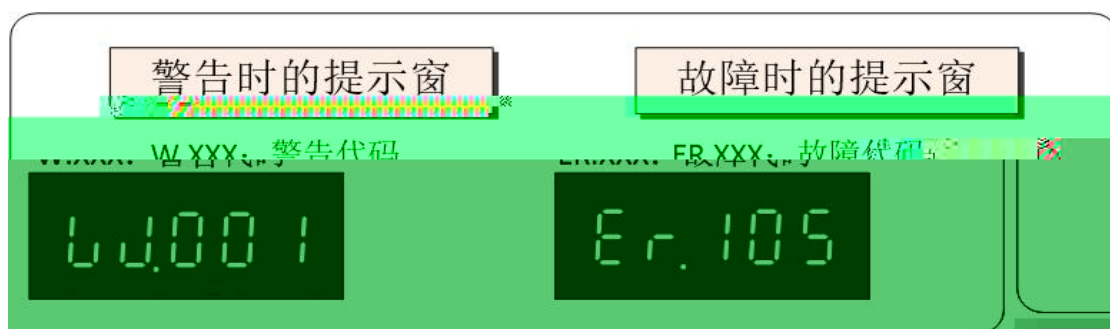


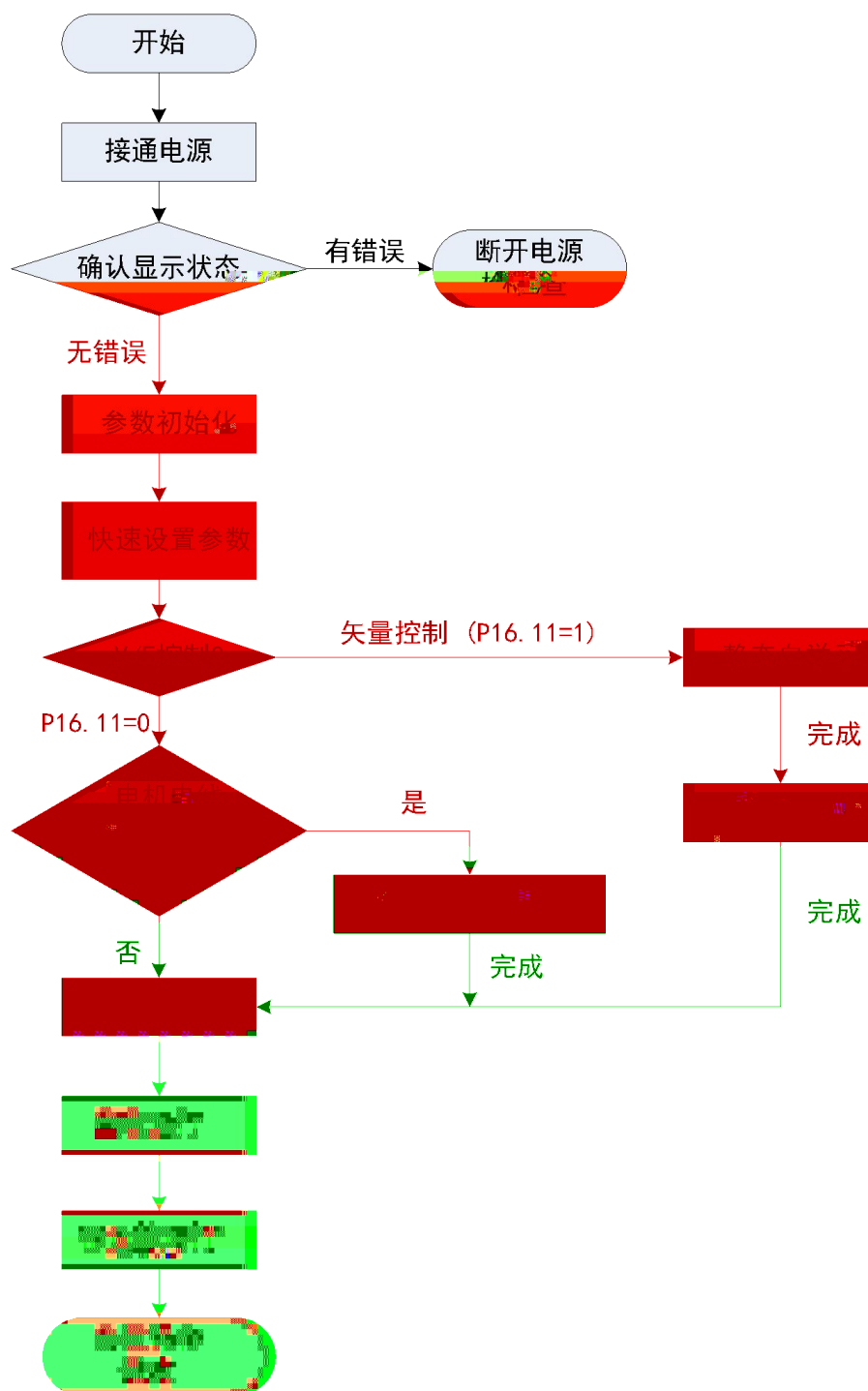




















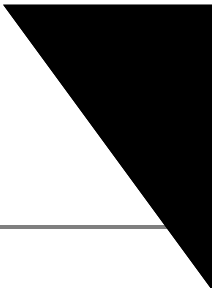
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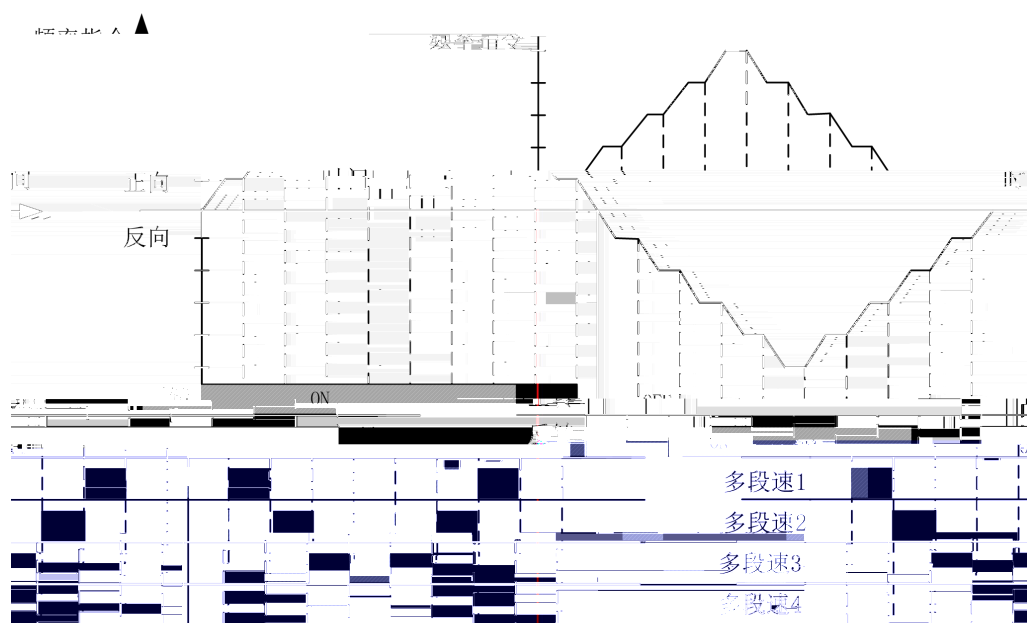


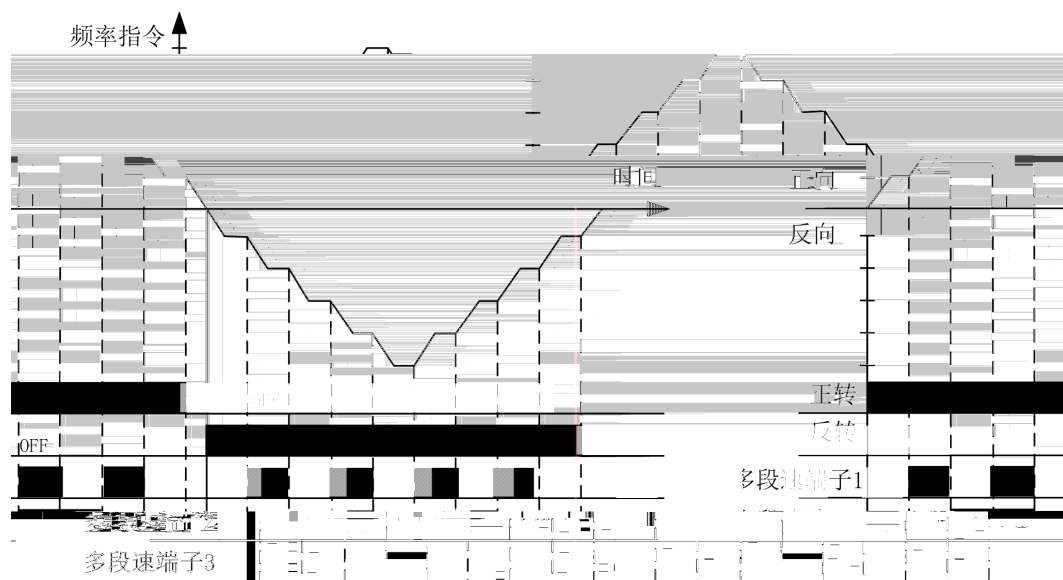


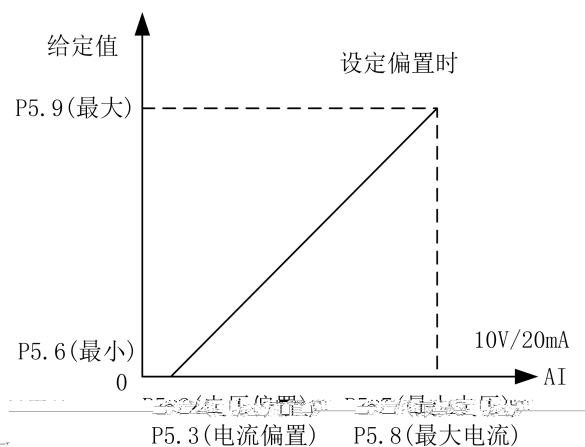
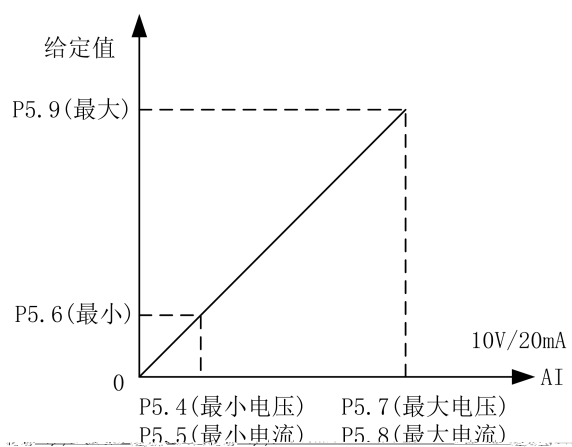
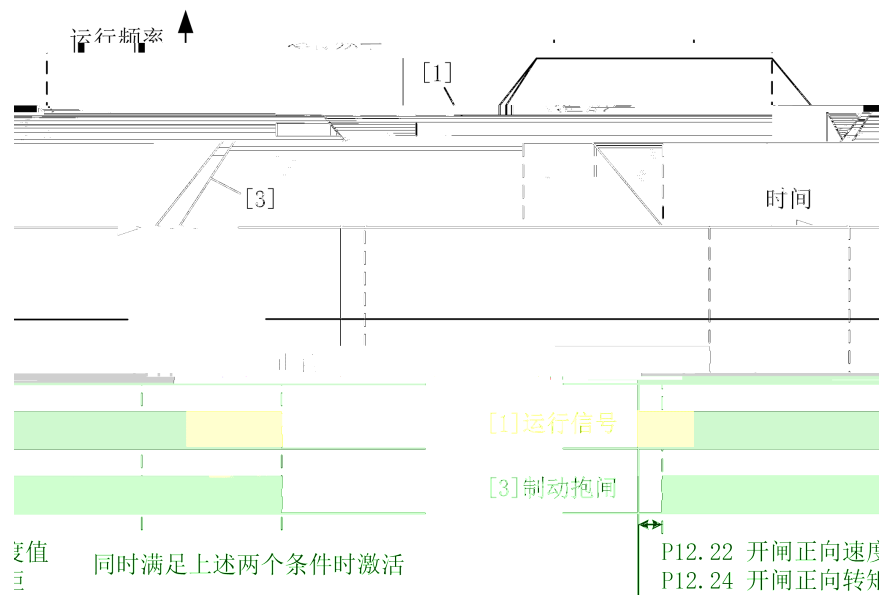


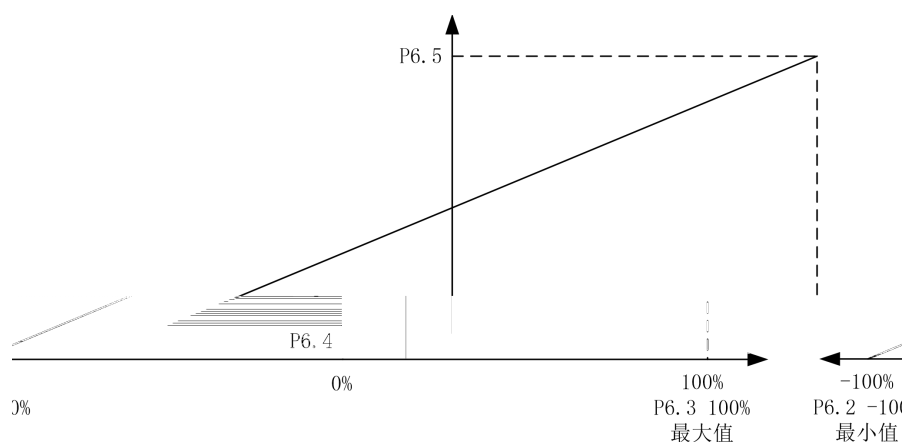
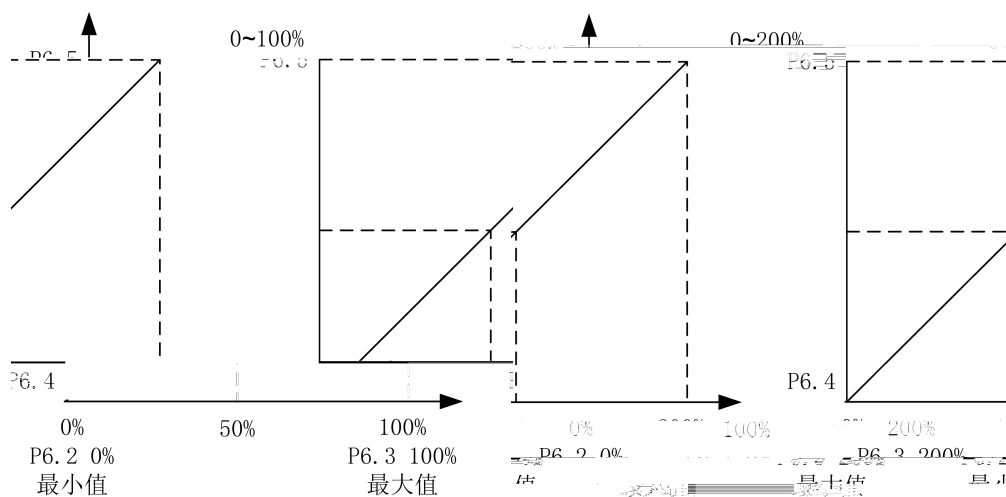






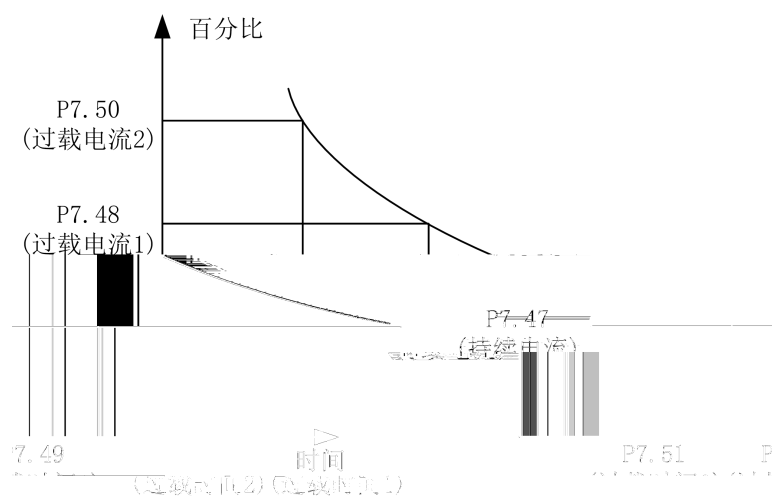






$$I_a + I_b + I_c$$

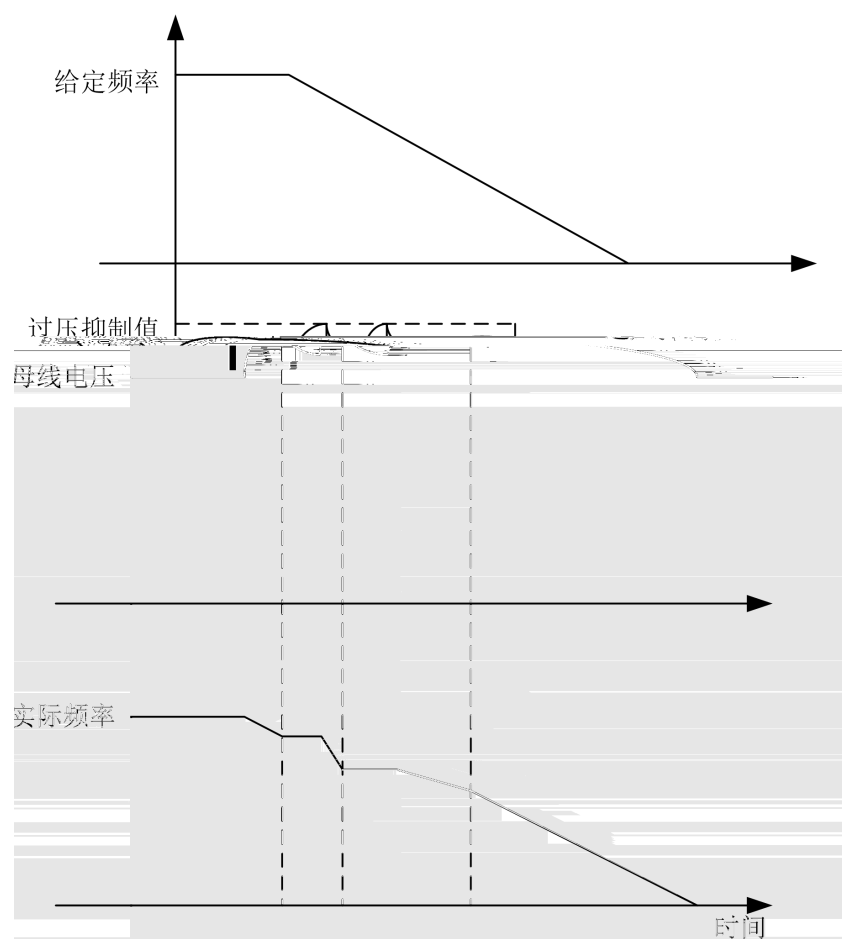
$$\frac{I_a + I_b + I_c}{P} > P$$

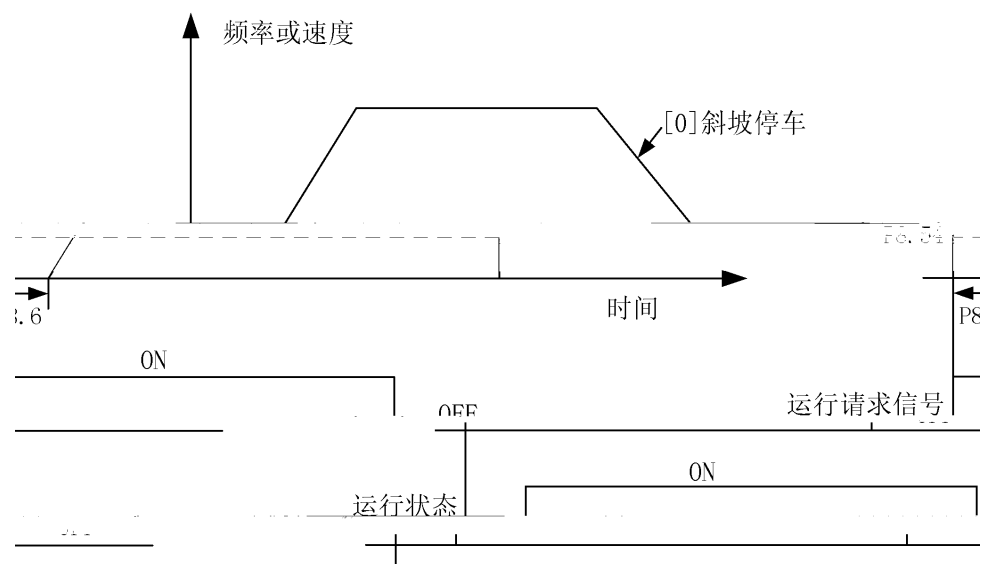
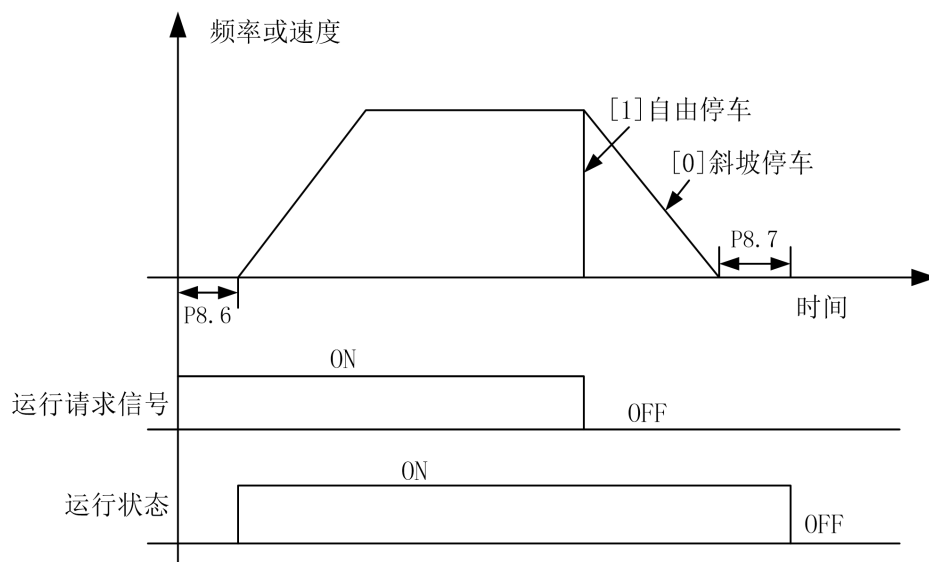


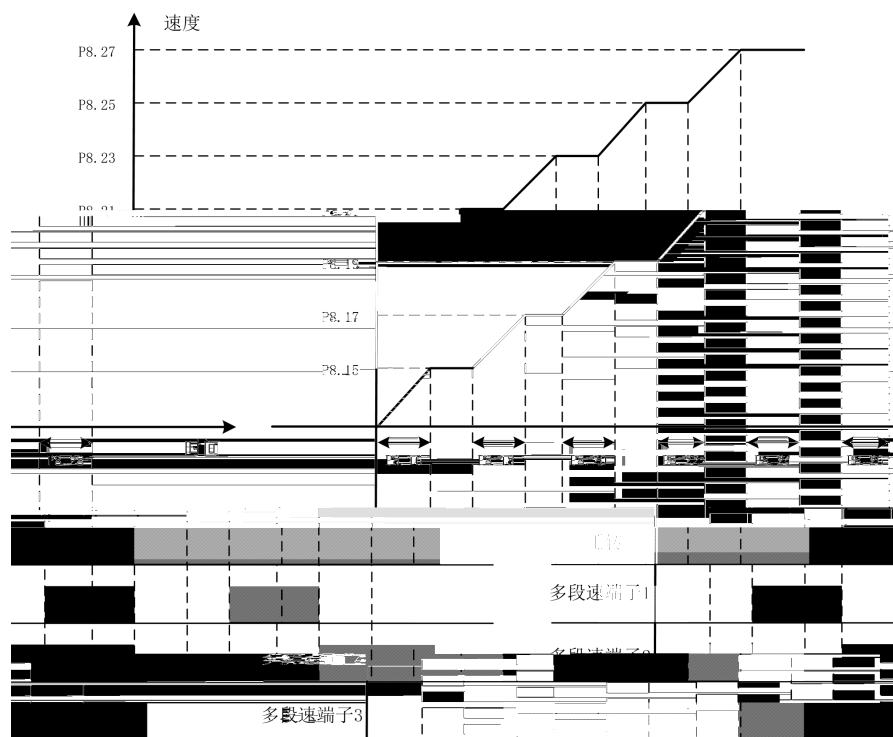
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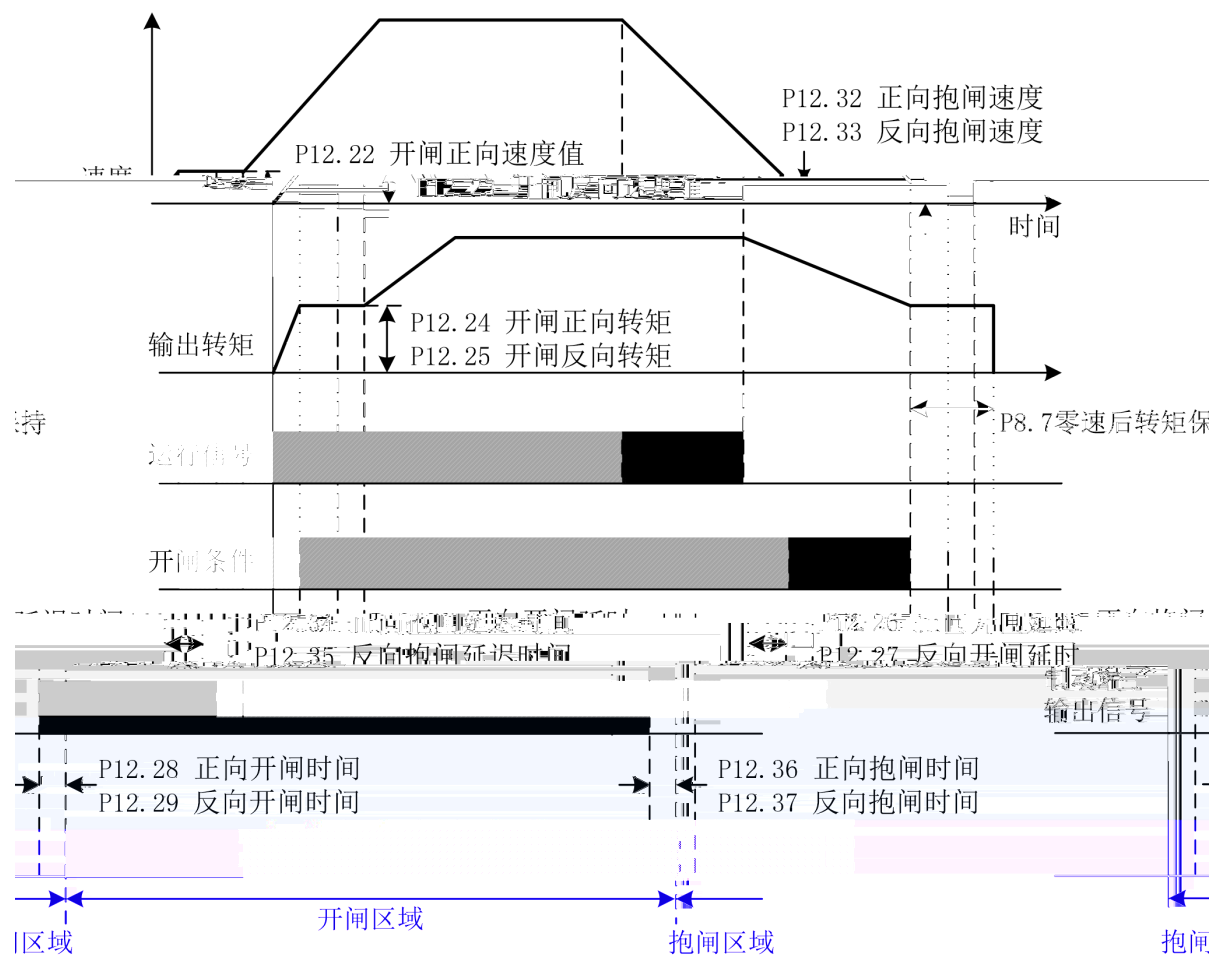
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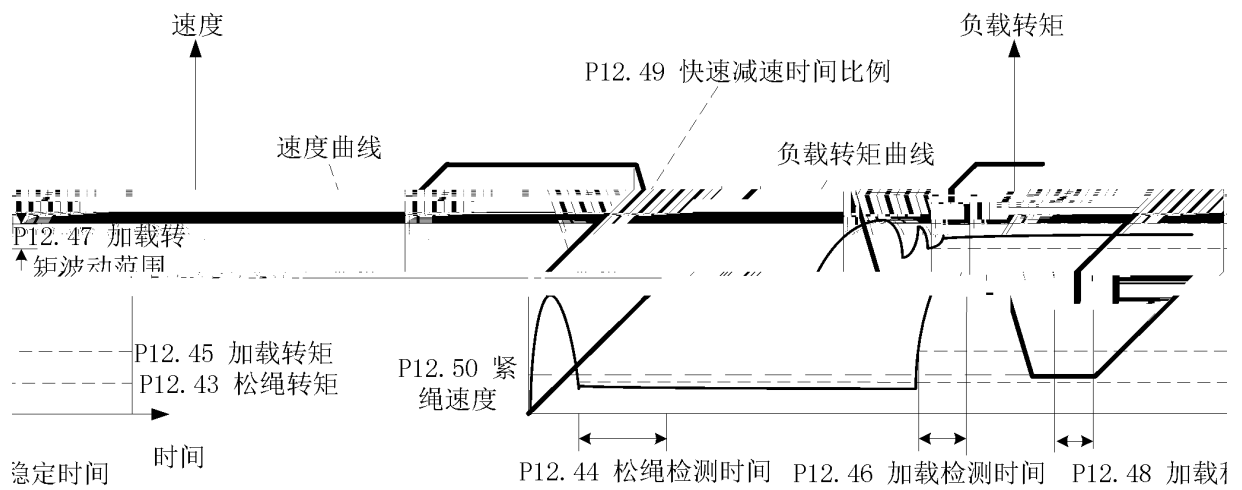




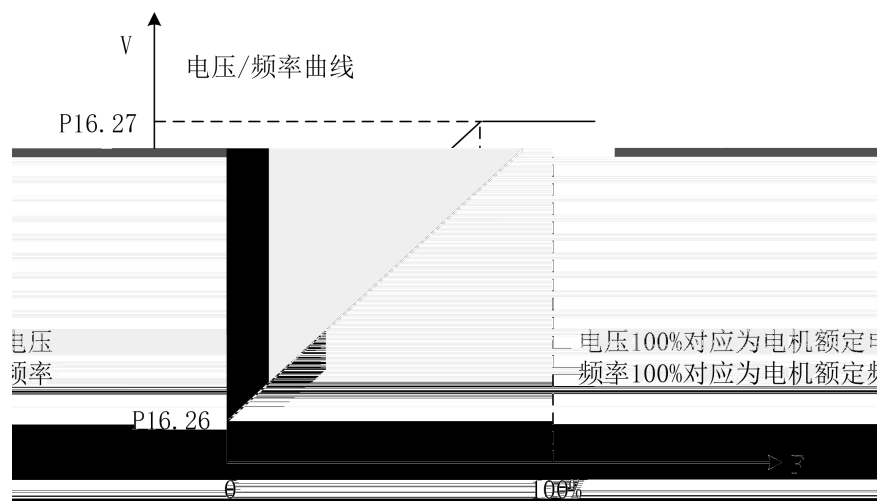




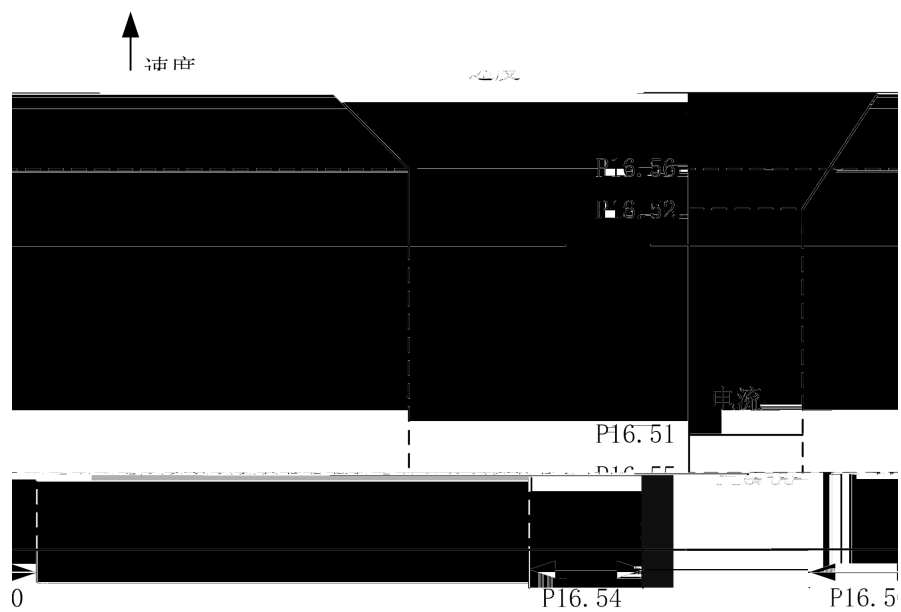






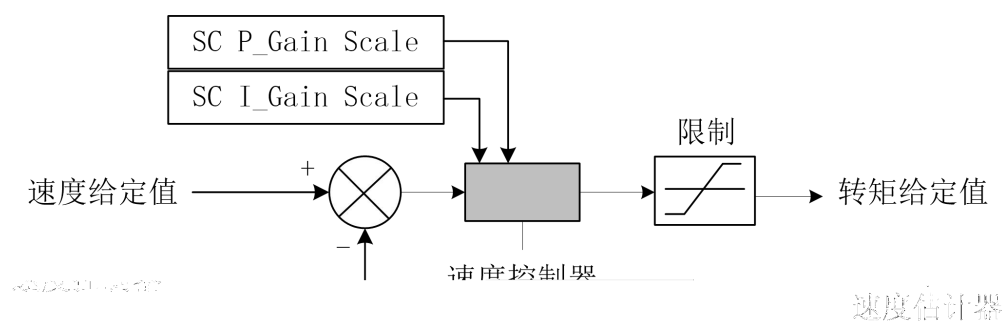
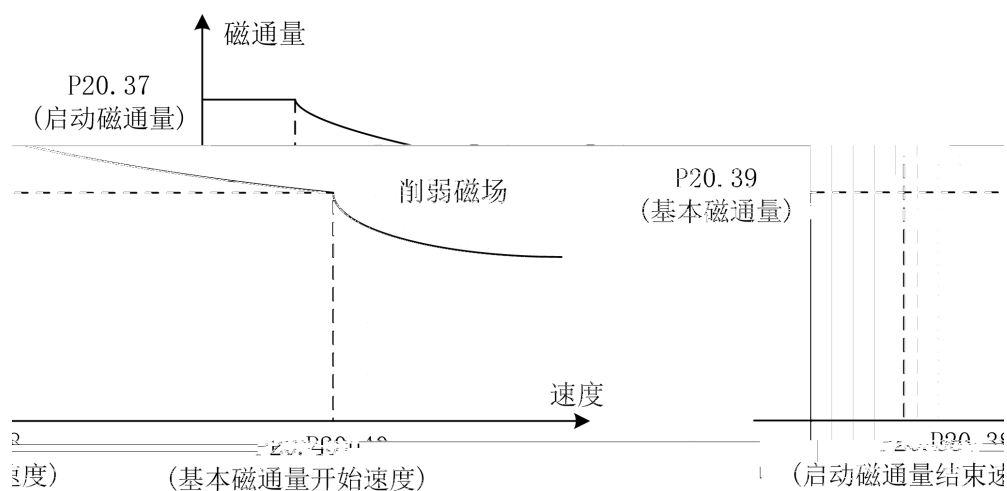
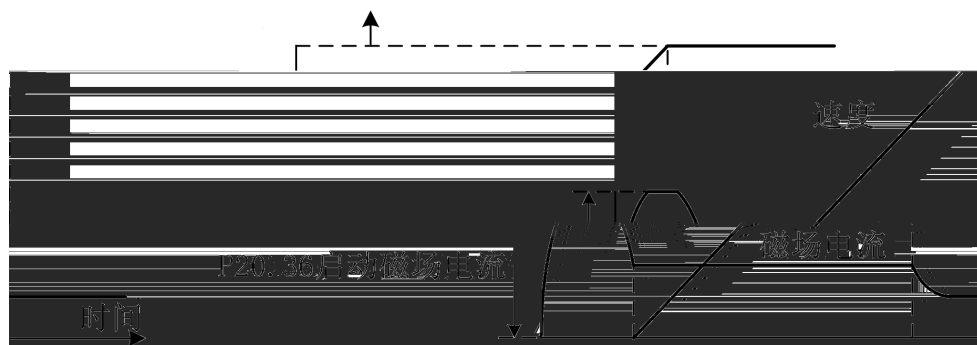


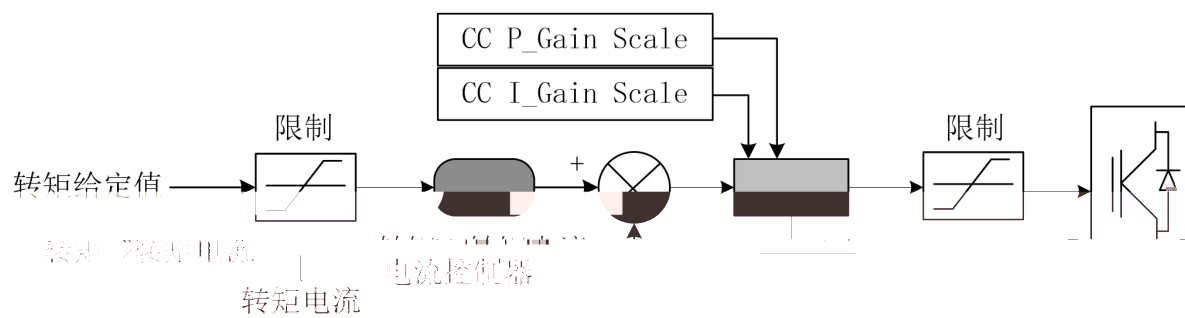
一、电压/频率曲线自动控制原理















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